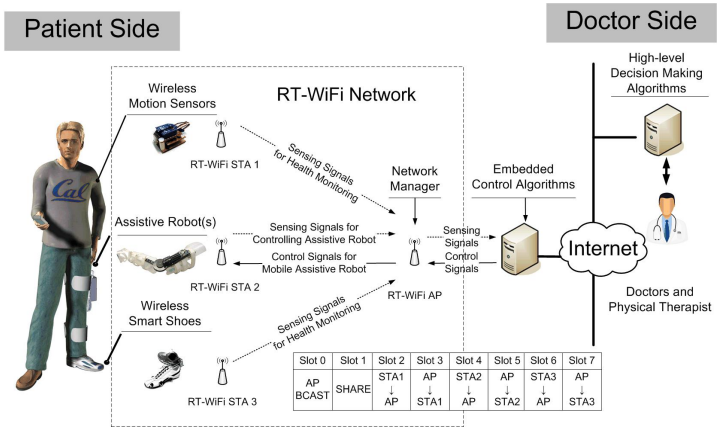
FD-PaS: A Fully Distributed Packet Scheduling Framework for Handling Disturbances in Real-Time Wireless Networks

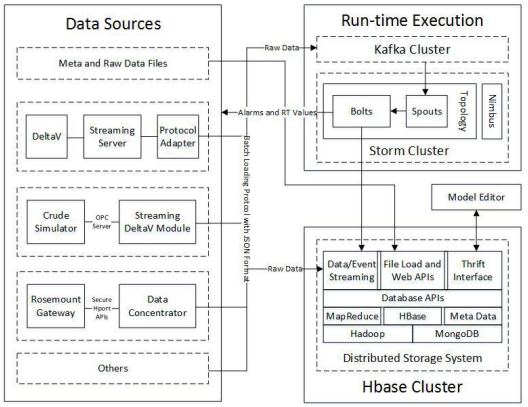
Tianyu Zhang[1,3], Tao Gong[2], Zelin Yun[2], Song Han[2],
Qingxu Deng[1], X. Sharon Hu[3]

[1]Northeastern University, China
[2]University of Connecticut, USA
[3]University of Notre Dame, USA

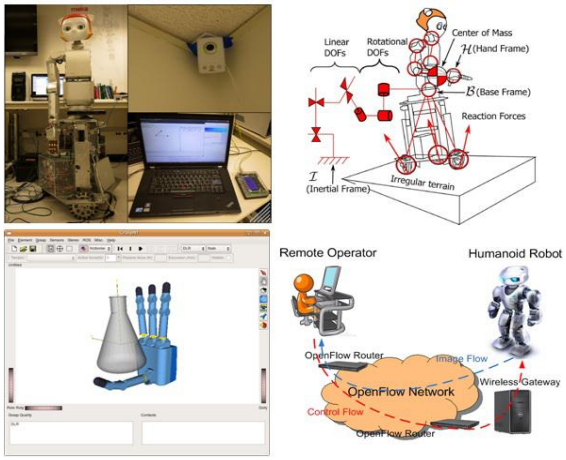
Real-Time Wireless Networks (RTWNs)



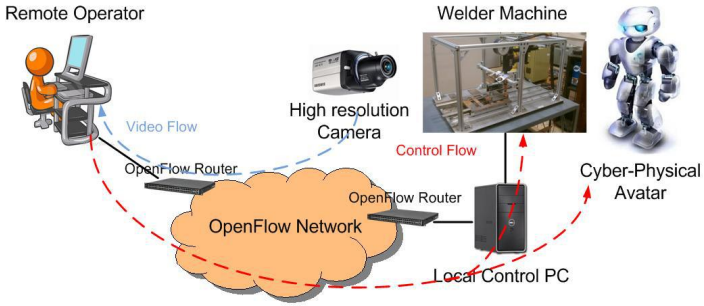
Network-based Rehabilitation System



Real-Time Analytics Platform for Process Control

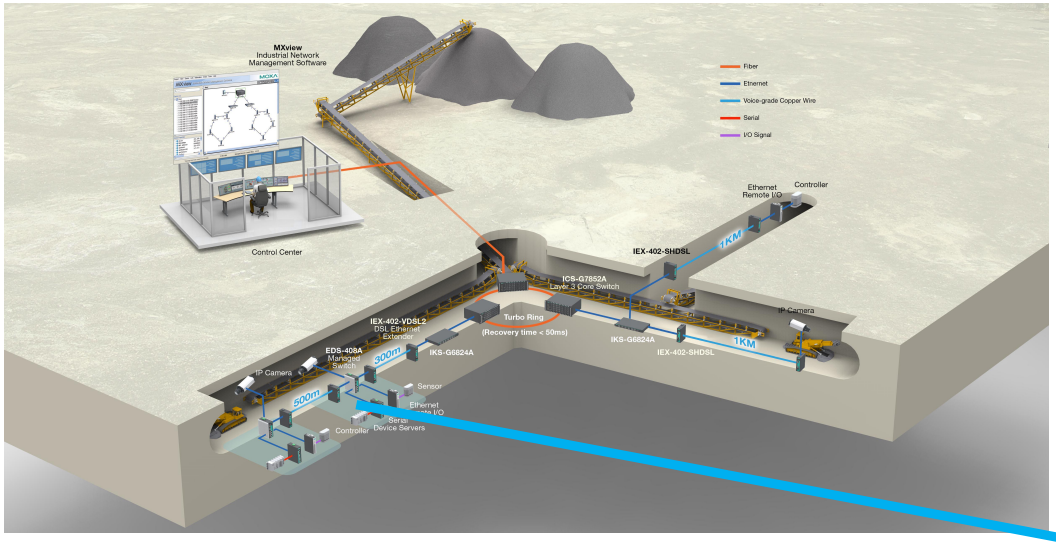


Cyber-physical Avatar



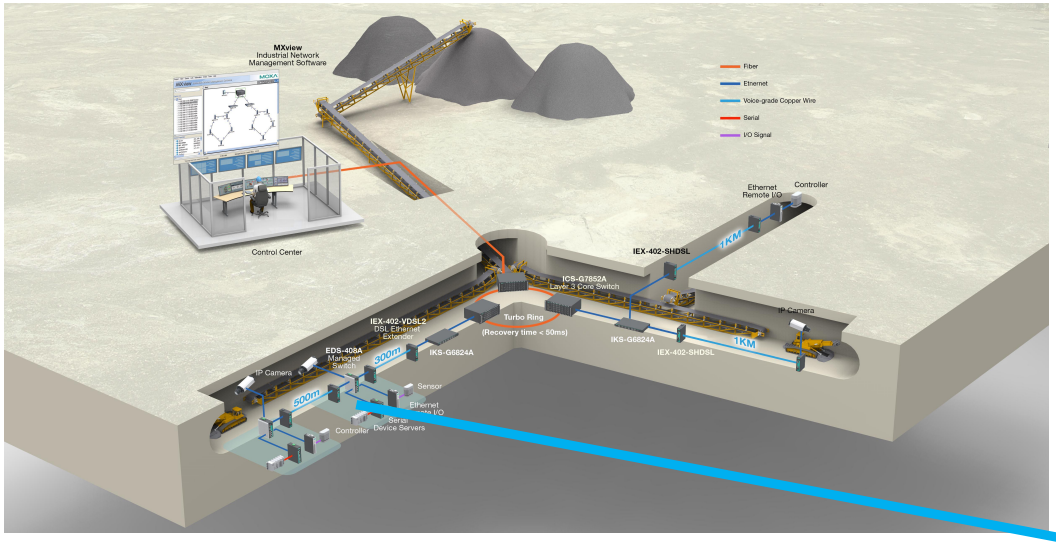
Remote and Real-time Welding System

An Example: Mining Monitoring System



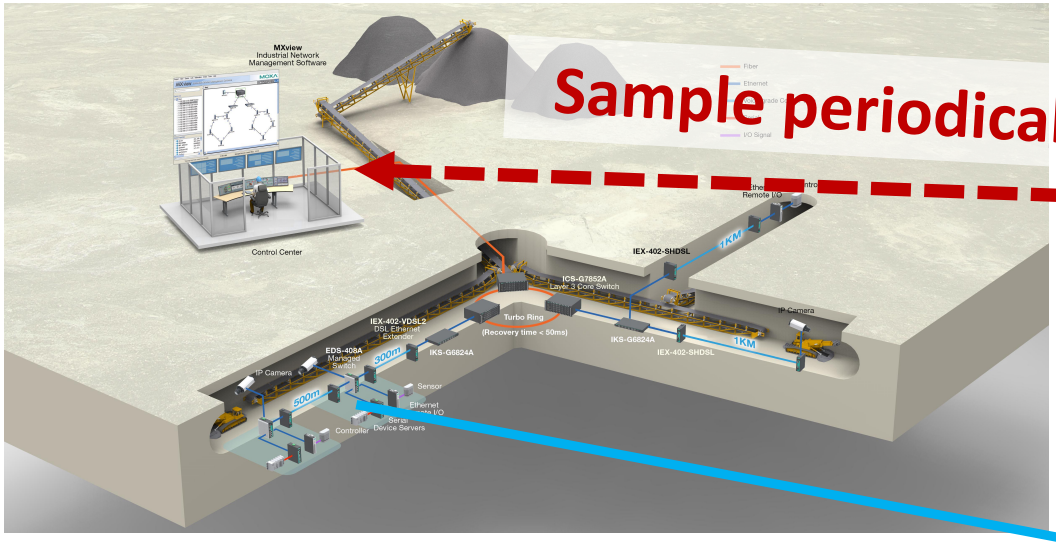
- Sensors monitor environment in real time
- Tasks are usually sampled and processed periodically with **fixed periods**

An Example: Mining Monitoring System



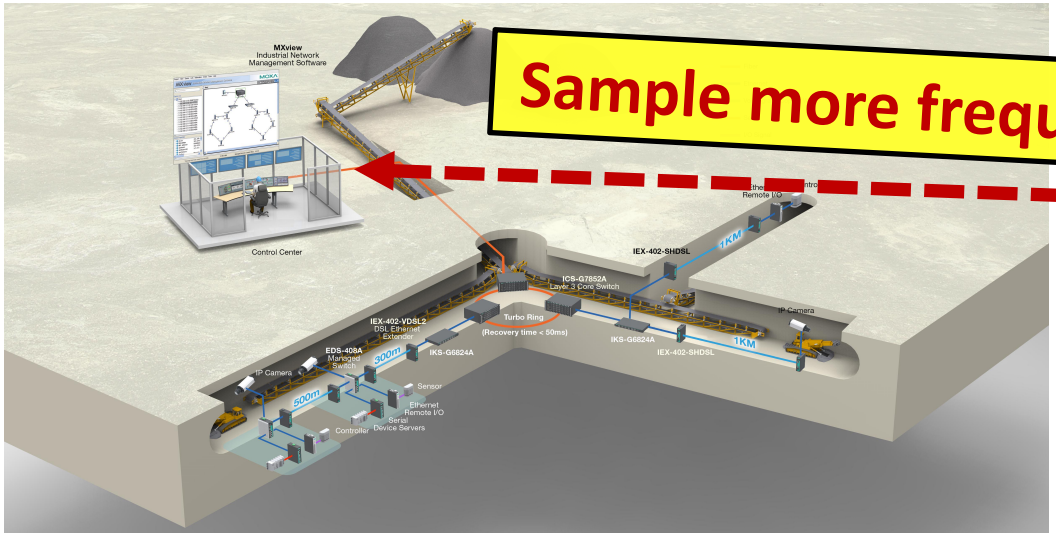
- Sensors monitor environment in real time
- Tasks are usually sampled and processed periodically with **fixed periods**

An Example: Mining Monitoring System



- Sensors monitor environment in real time
- Tasks are usually sampled and processed periodically with **fixed periods**

An Example: Mining Monitoring System



- **External disturbance**: unexpected changes in temperature/pressure, etc.
- Require more frequent monitoring/response

What We Want to Achieve?

Requirements of a RTWN

- Data must be collected timely

What We Want to Achieve?

Requirements of a RTWN

- Data must be collected timely
- Deployed over large area

What We Want to Achieve?

Requirements of a RTWN

- Data must be collected timely
- Deployed over large area
- Fast response to disturbance

What We Want to Achieve?

Requirements of a RTWN

- Data must be collected timely
- Deployed over large area
- Fast response to disturbance
- High QoS (how well it satisfies real-time deadlines)

What We Want to Achieve?

Requirements of a RTWN

- Data must be collected timely
- Deployed over large area
- Fast response to disturbance
- High QoS (how well it satisfies real-time deadlines)

Our Design

- On-line scheduling
- Fully distributed
- Guaranteed fast response
- Fewest dropped packets

Outline

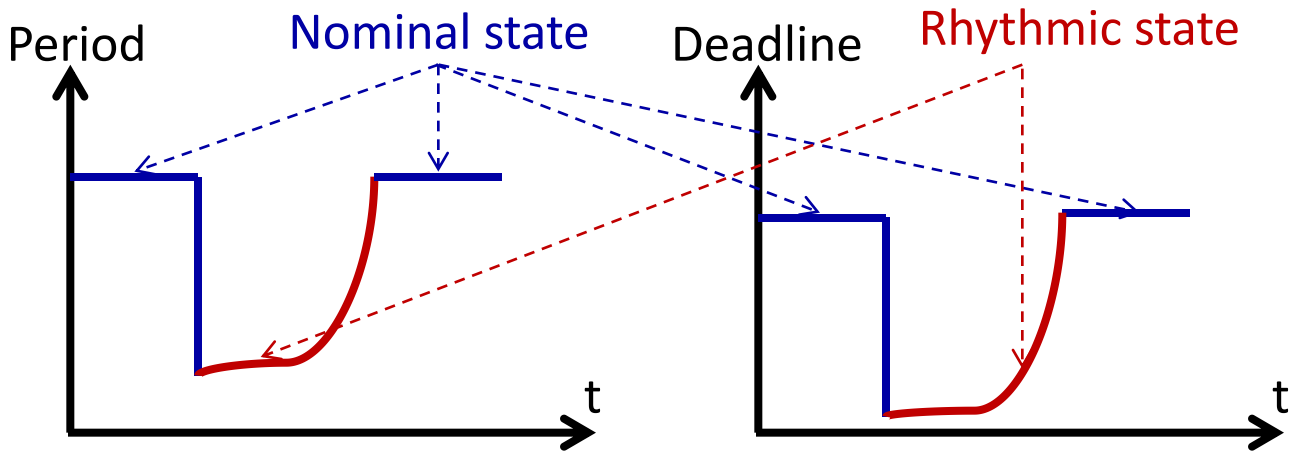
- **System model & related work**
- Fully distrubuted packet scheduling framework (FD-PaS)
- Experimental evaluation

Model Disturbance

- When nothing happens
  - All tasks follow regular periods
- When disturbance occurs
  - The corresponding task follows a specific release pattern

Rhythmic Model

- When nothing happens
  - All tasks follow regular periods
- When disturbance occurs
  - The corresponding task follows a specific release pattern

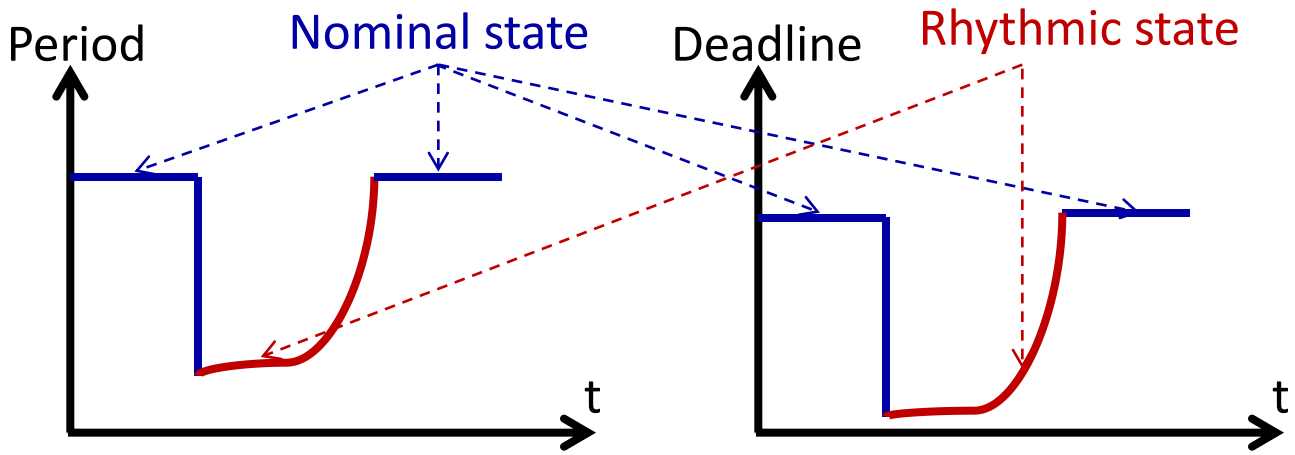


J. Kim, K. Lakshmanan and R. Rajkumar, *ICCPS*, 2012

Rhythmic Model

- When nothing happens
  - All tasks follow regular periods
- When disturbance occurs
  - The corresponding task follows a specific release pattern

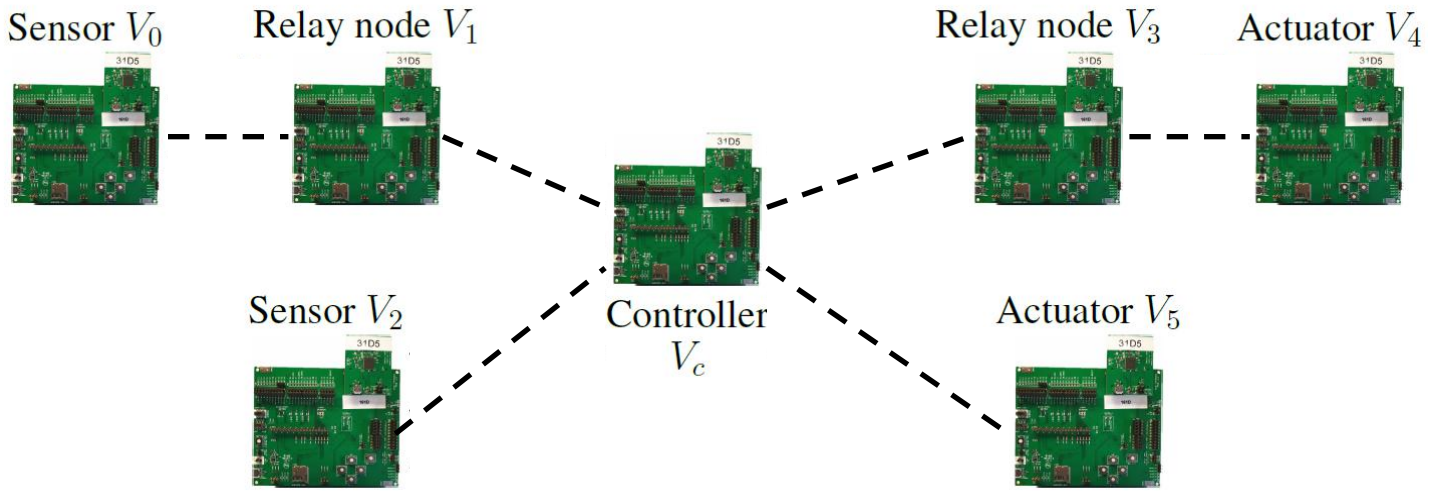
Works for other models



J. Kim, K. Lakshmanan and R. Rajkumar, *ICCPS*, 2012

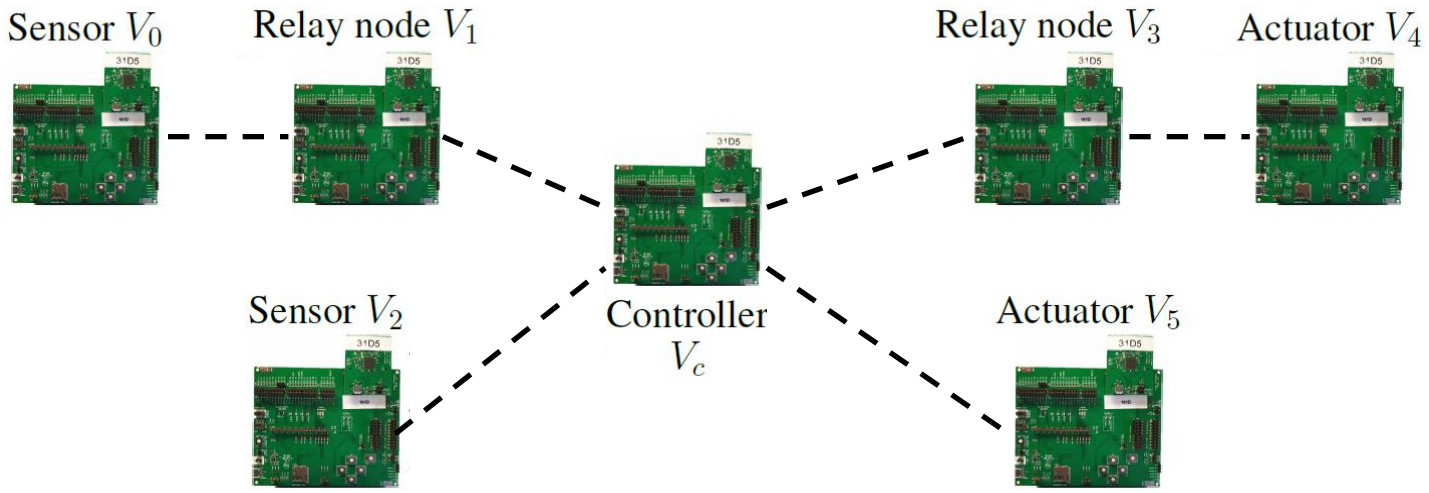
System Model

- RTWN infrastructure
  - A controller, sensors, relay nodes and actuators sharing a channel
  - Nodes have computing capability



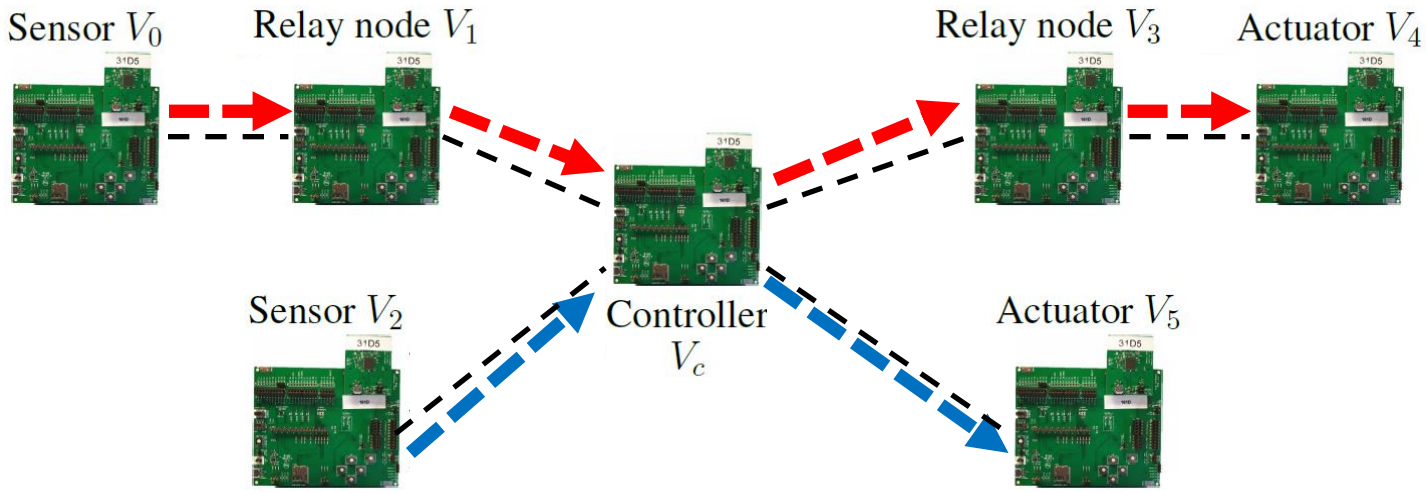
System Model

- RTWN infrastructure
  - A controller, sensors, relay nodes and actuators sharing a channel
  - Nodes have computing capability
- Task model
  - Unicast tasks (periodic and rhythmic) release infinite packets
  - One disturbance in the system at a given time

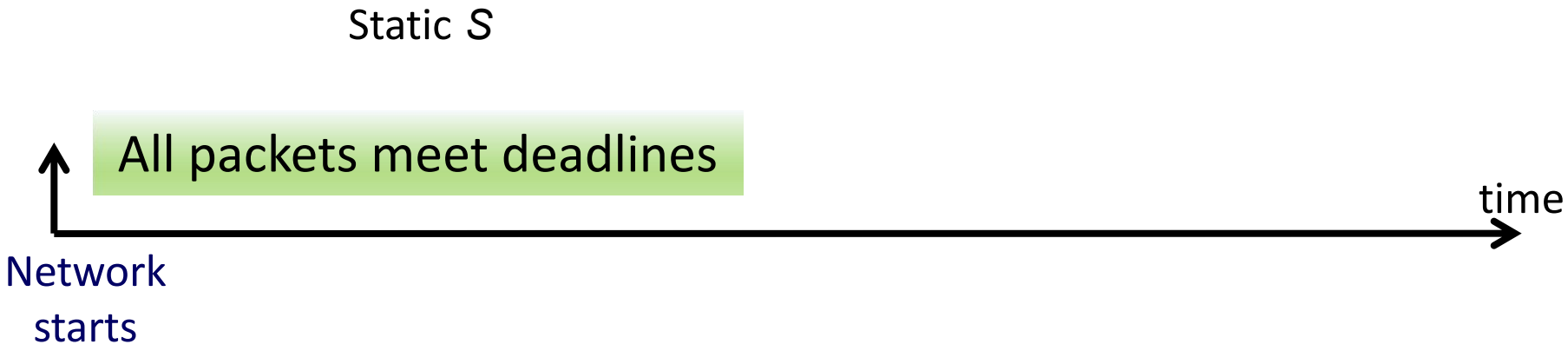


System Model

- RTWN infrastructure
  - A controller, sensors, relay nodes and actuators sharing a channel
  - Nodes have computing capability
- Task model
  - Unicast tasks (periodic and rhythmic) release infinite packets
  - One disturbance in the system at a given time
  - Routing path: every task passes through the controller

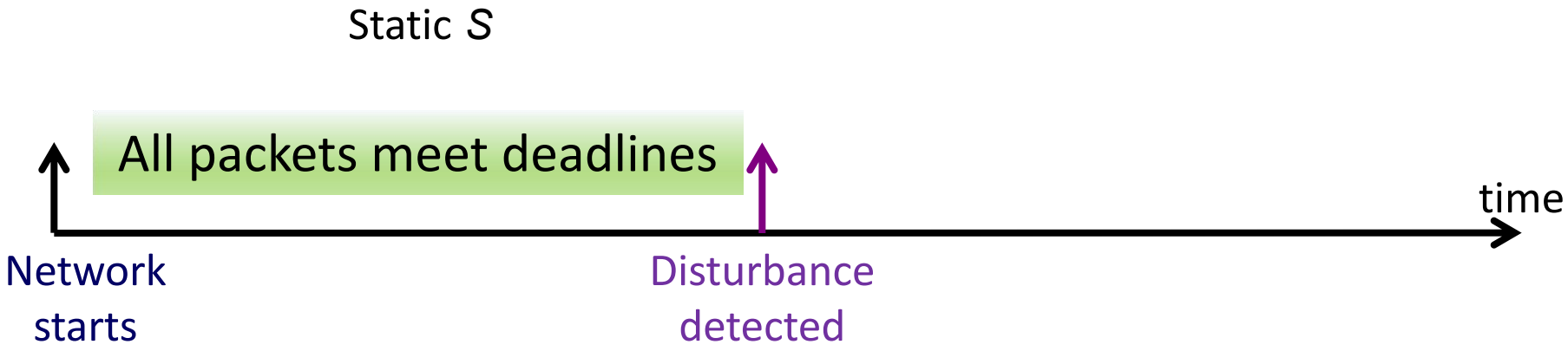


Problem Overview



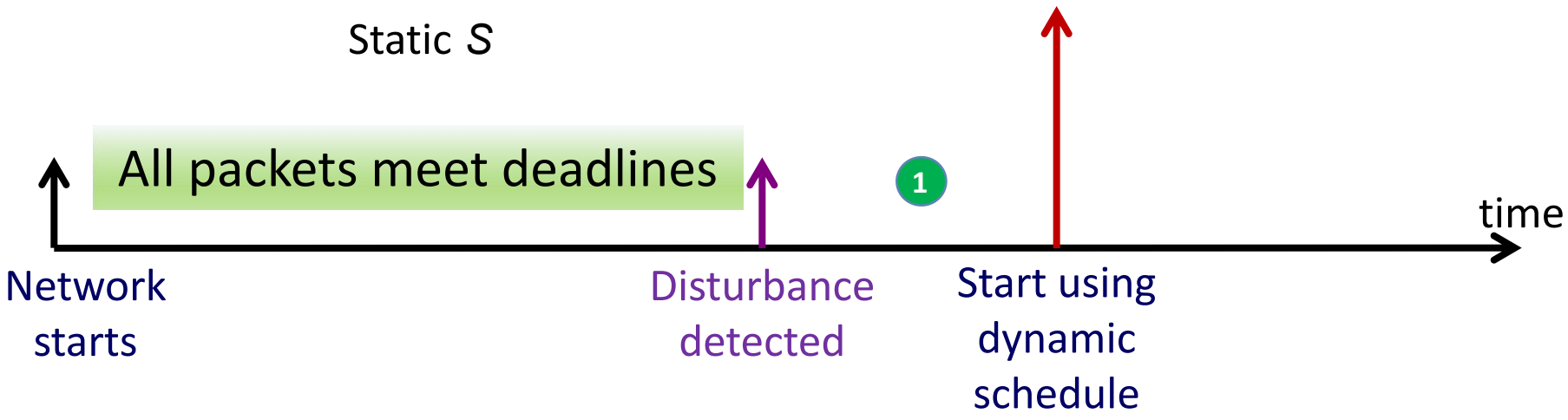
- No disturbance
  - Use a feasible static schedule

Problem Overview



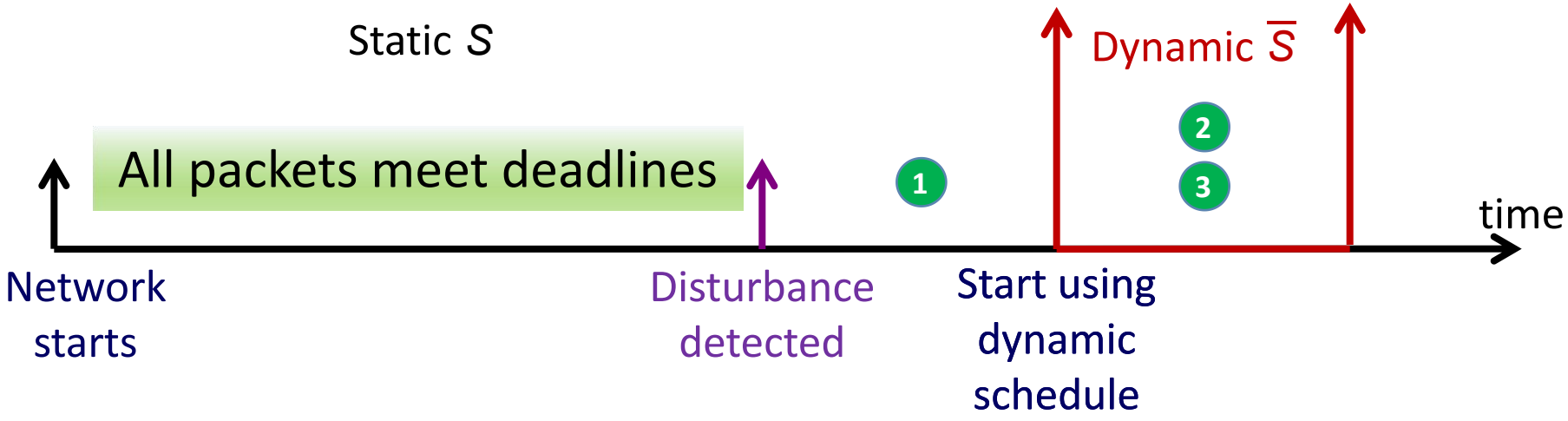
- No disturbance
  - Use a feasible static schedule
- Upon detection of a disturbance, determine a dynamic schedule

Problem Overview



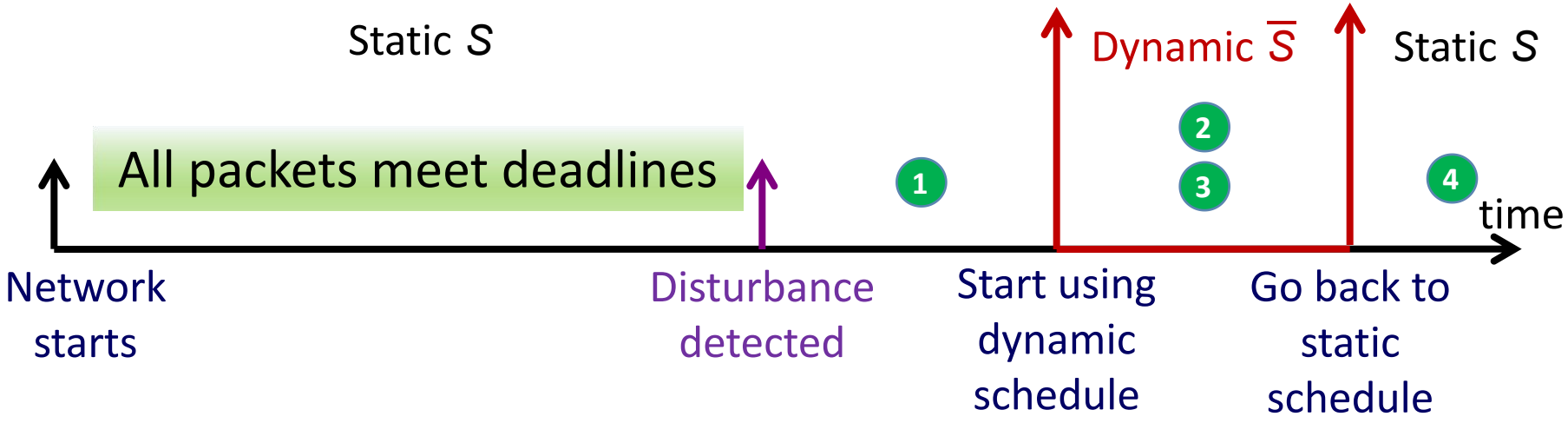
- No disturbance
  - Use a feasible static schedule
- Upon detection of a disturbance, determine a dynamic schedule
  - 1 Guaranteed fast response to the disturbance

Problem Overview



- No disturbance
  - Use a feasible static schedule
- Upon detection of a disturbance, determine a dynamic schedule
  1. Guaranteed fast response to the disturbance
  2. All rhythmic packets meet their deadlines
  3. Fewest periodic packets are dropped

Problem Overview

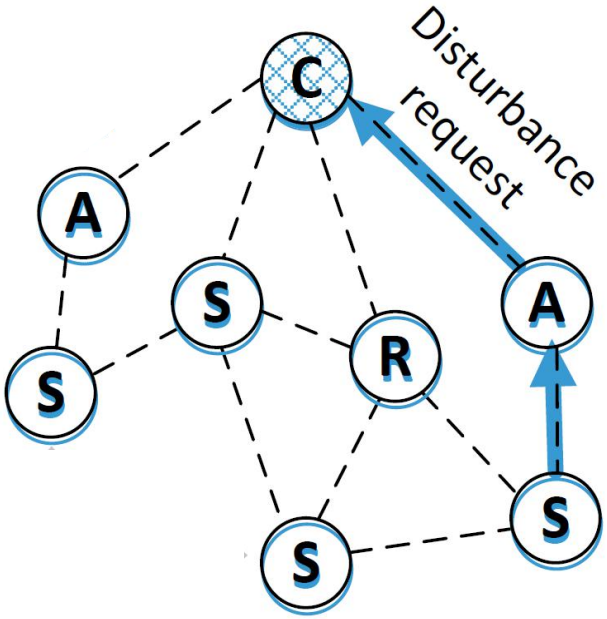


- No disturbance
  - Use a feasible static schedule
- Upon detection of a disturbance, determine a dynamic schedule
  1. Guaranteed fast response to the disturbance
  2. All rhythmic packets meet their deadlines
  3. Fewest periodic packets are dropped
  4. System can safely return to the nominal mode

Centralized Approach

OLS

- Sensor sends a rhythmic event request to the controller/gateway

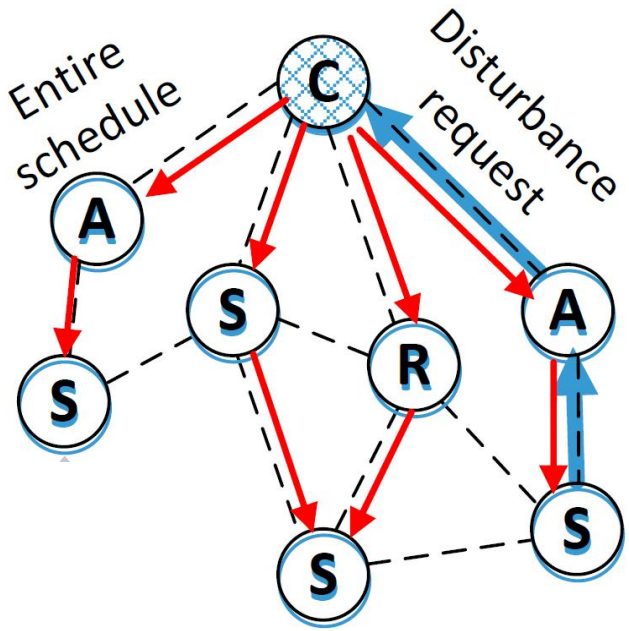


S. Hong, X. Hu, T. Gong and S. Han, *ECRTS* 2015

Centralized Approach

OLS

- Sensor sends a rhythmic event request to the controller/gateway
- Gateway generates and broadcasts a dynamic schedule

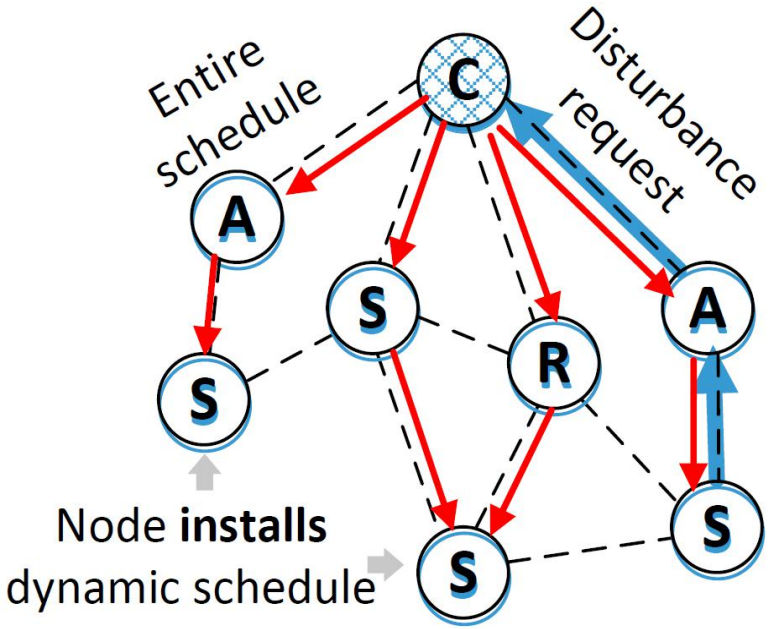


S. Hong, X. Hu, T. Gong and S. Han, *ECRTS* 2015

Centralized Approach

OLS

- Sensor sends a rhythmic event request to the controller/gateway
- Gateway generates and broadcasts a dynamic schedule
- Nodes install and follow a dynamic schedule

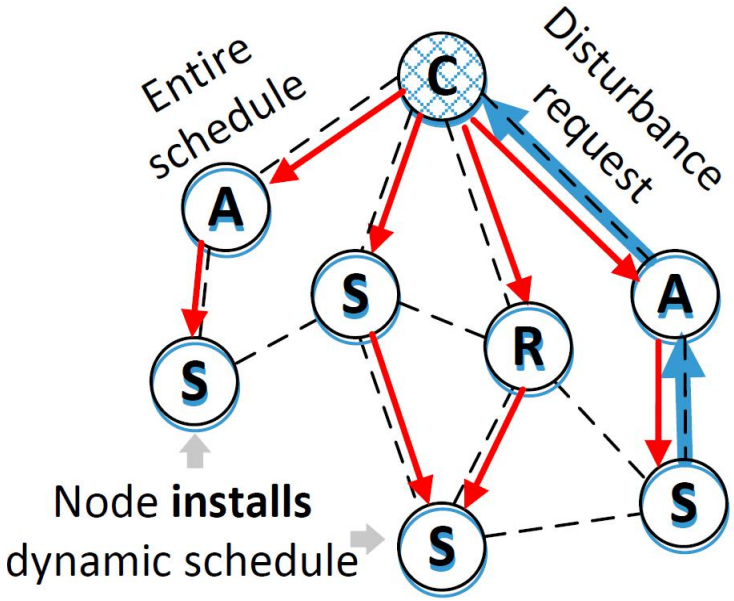


S. Hong, X. Hu, T. Gong and S. Han, *ECRTS* 2015

Centralized Approach

OLS

- Sensor sends a rhythmic event request to the controller/gateway
- Gateway generates and broadcasts a dynamic schedule
- Nodes install and follow a dynamic schedule



Dynamic programming

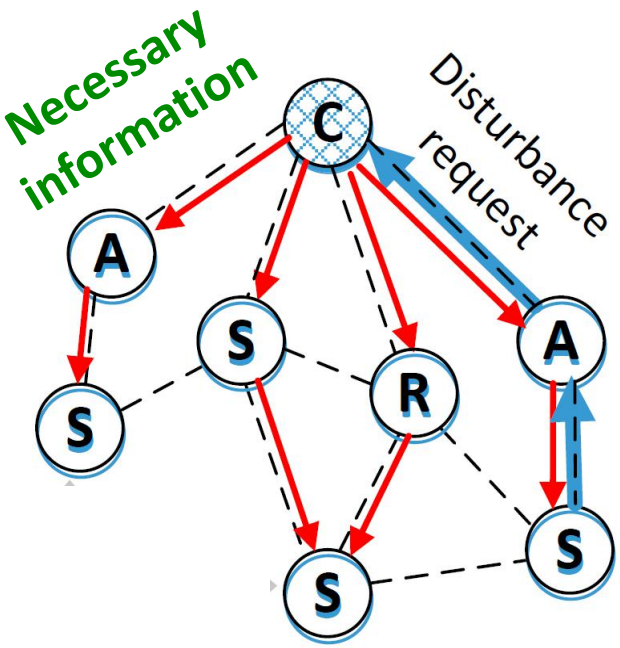
Drop more packets than necessary

S. Hong, X. Hu, T. Gong and S. Han, *ECRTS* 2015

Hybrid Approach

D²-PaS

- Sensor sends a rhythmic event request to the controller/gateway
- Gateway generates and broadcasts **only necessary information**

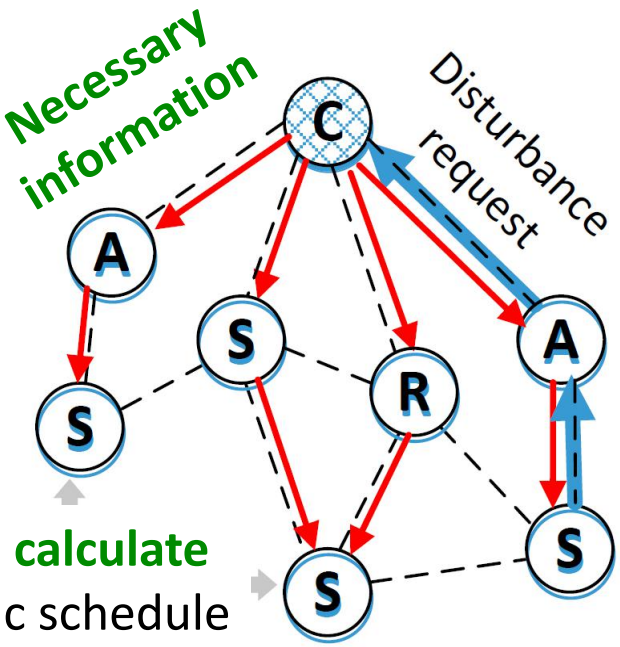


T. Zhang, T. Gong, C. Gu, S. Han, Q. Deng and X. Hu, *RTAS* 2017

Hybrid Approach

D²-PaS

- Sensor sends a rhythmic event request to the controller/gateway
- Gateway generates and broadcasts **only necessary information**
- Nodes **calculate** a dynamic schedule



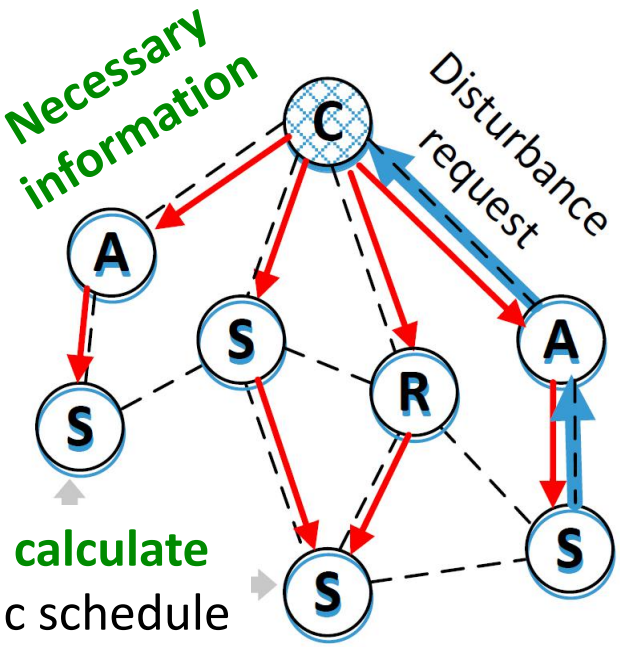
Nodes **calculate** dynamic schedule

T. Zhang, T. Gong, C. Gu, S. Han, Q. Deng and X. Hu, *RTAS* 2017

Hybrid Approach

D²-PaS

- Sensor sends a rhythmic event request to the controller/gateway
- Gateway generates and broadcasts **only necessary information**
- Nodes **calculate** a dynamic schedule



Nodes **calculate** dynamic schedule

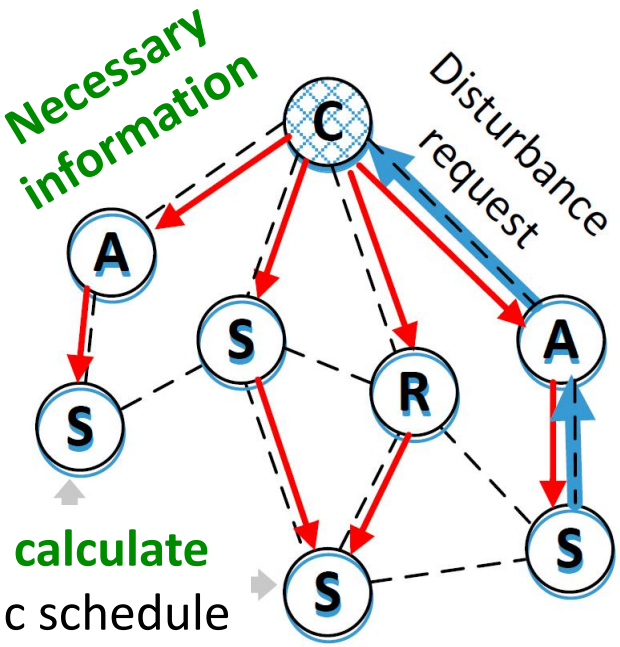
Drop fewer periodic packets

T. Zhang, T. Gong, C. Gu, S. Han, Q. Deng and X. Hu, *RTAS* 2017

Hybrid Approach

D²-PaS

- Sensor sends a rhythmic event request to the controller/gateway
- Gateway generates and broadcasts **only necessary information**
- Nodes **calculate** a dynamic schedule



Drop fewer periodic packets

Long response time to disturbance

Rely on a single point (gateway)

T. Zhang, T. Gong, C. Gu, S. Han, Q. Deng and X. Hu, *RTAS* 2017

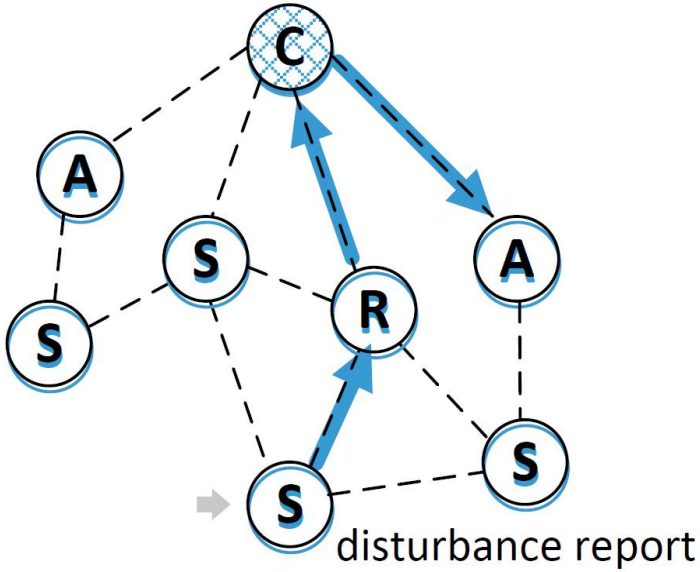
Outline

- System model & related work
- **Fully distrubuted packet scheduling framework (FD-Pas)**
  - **Overview**
  - **MP-MAC**
  - **Dynamic schedule generation**
- Experimental evaluation

Fully Distributed Approach

FD-PaS

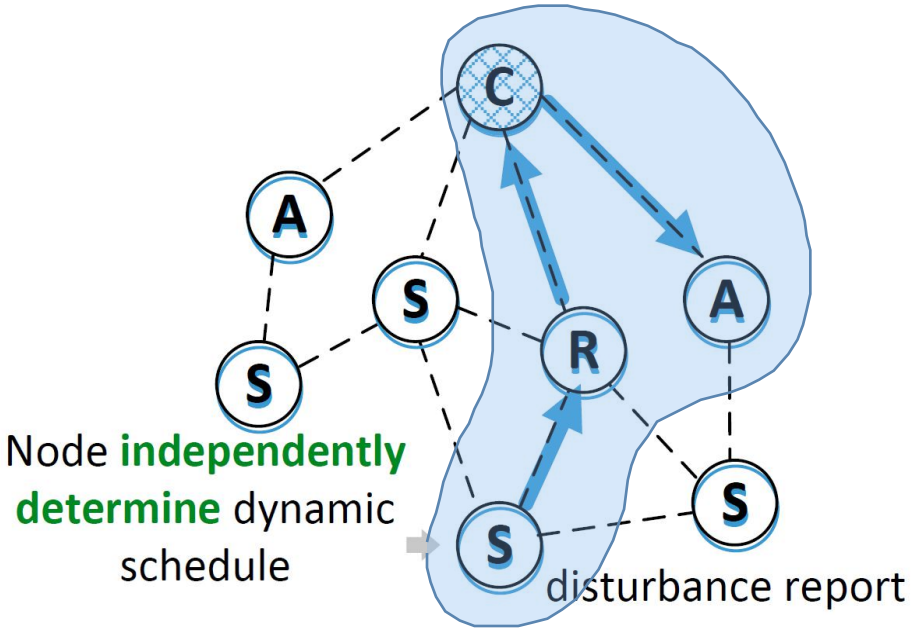
- Sensor sends a rhythmic event report only to **necessary nodes**



Fully Distributed Approach

FD-PaS

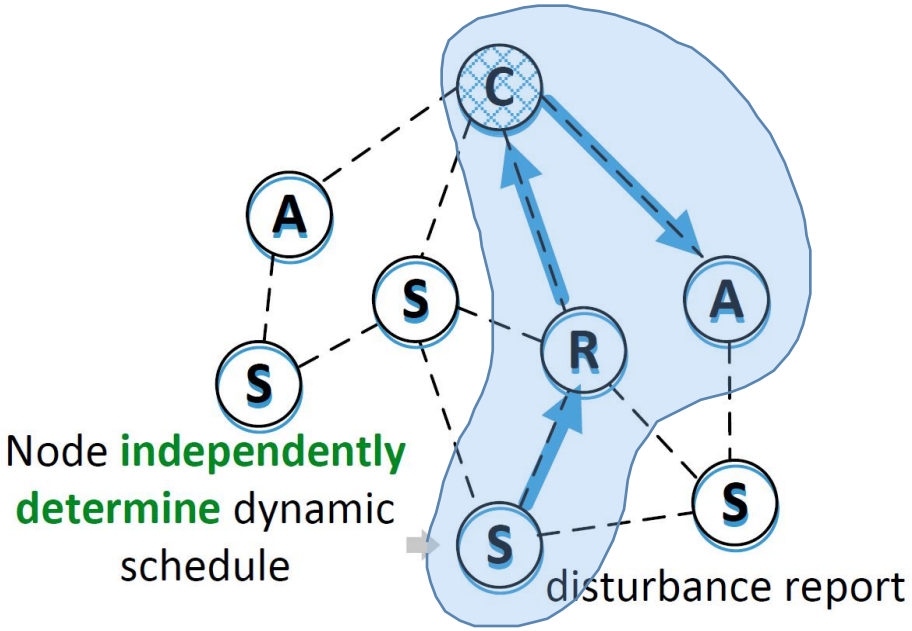
- Sensor sends a rhythmic event report only to **necessary nodes**
- Nodes **independently determine** dynamic schedule locally



Fully Distributed Approach

FD-PaS

- Sensor sends a rhythmic event report only to **necessary nodes**
- Nodes **independently determine** dynamic schedule locally



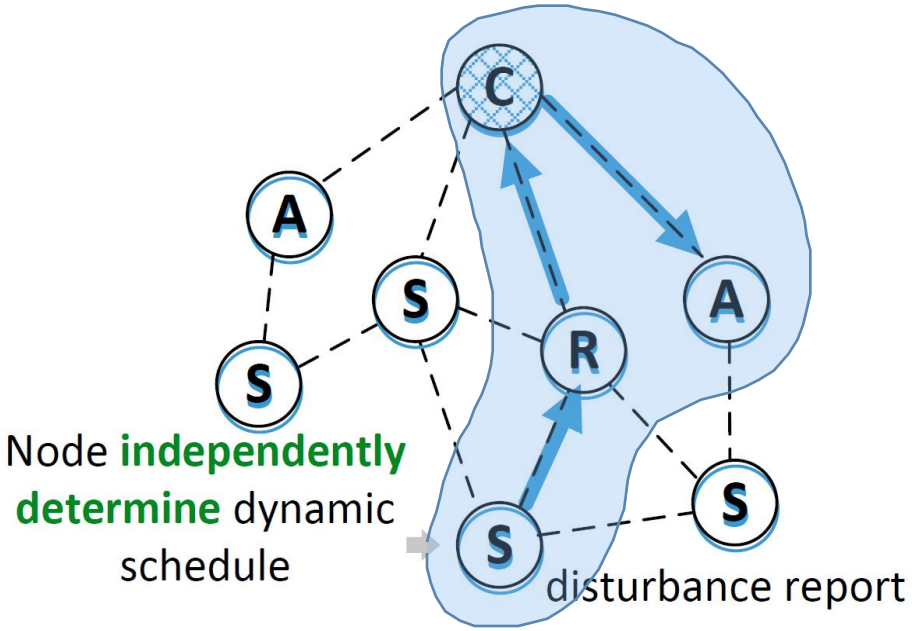
Fast response to disturbance

Don't rely on any single point

Fully Distributed Approach

FD-PaS

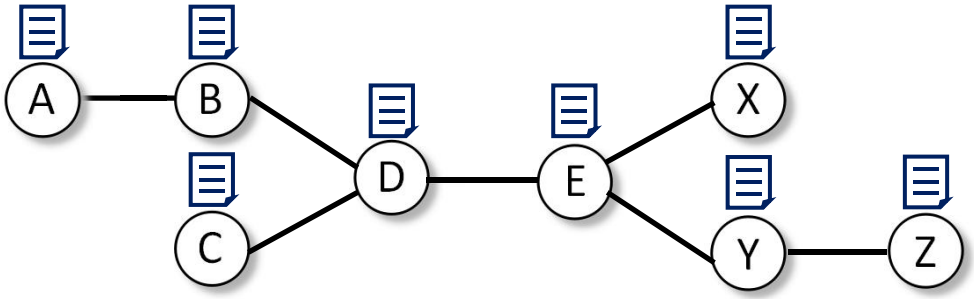
- Sensor sends a rhythmic event report only to **necessary nodes**
- Nodes **independently determine** dynamic schedule locally



Q1. **Which** nodes need to know the disturbance?

Q2. **How** these nodes know the disturbance?

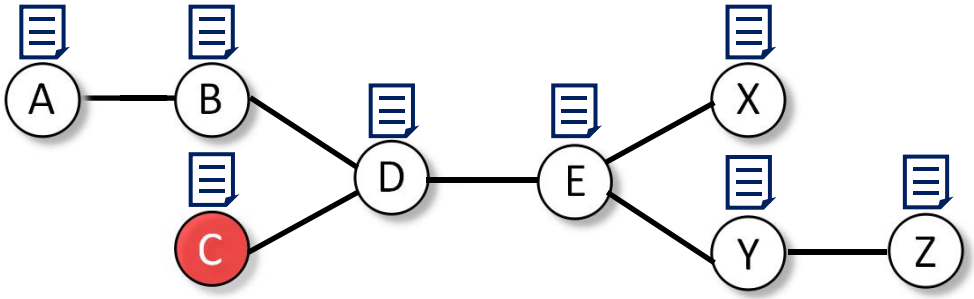
FD-PaS Framework

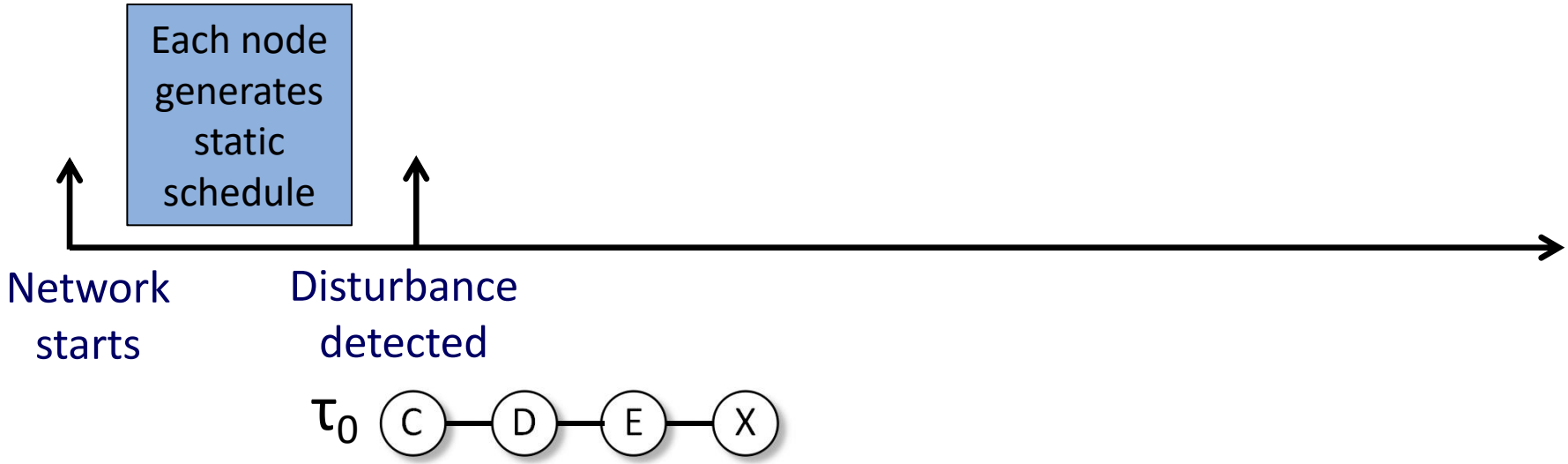


Each node generates static schedule

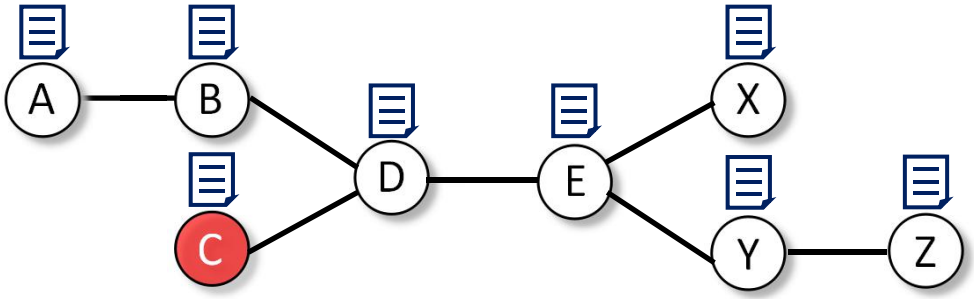
Network starts

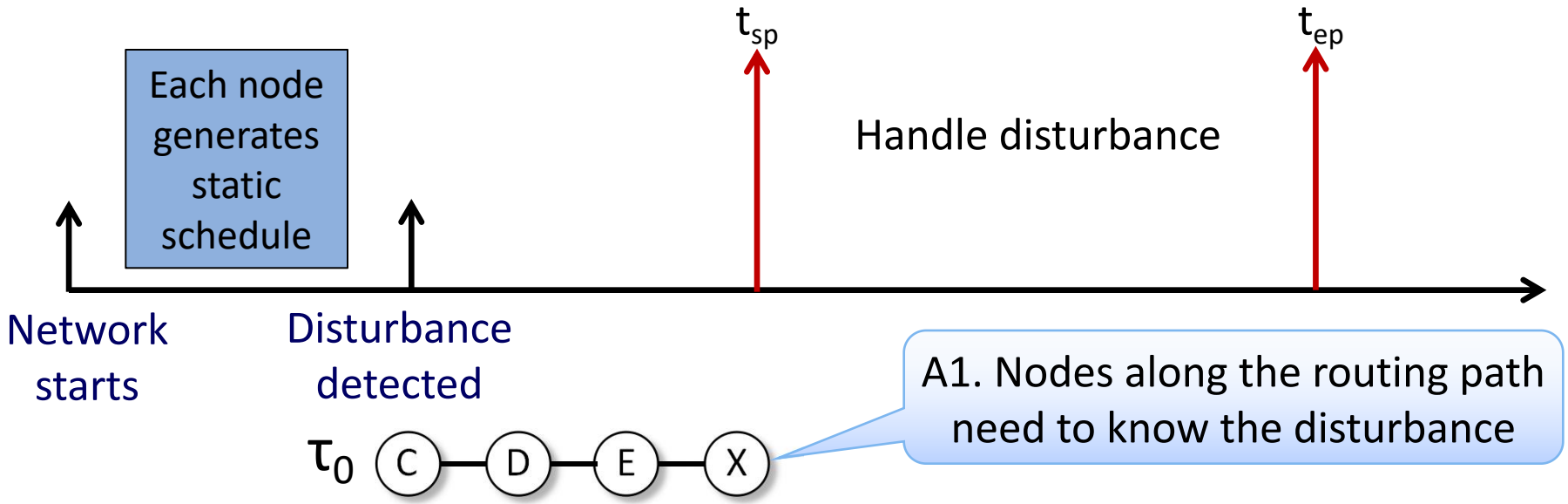
FD-PaS Framework



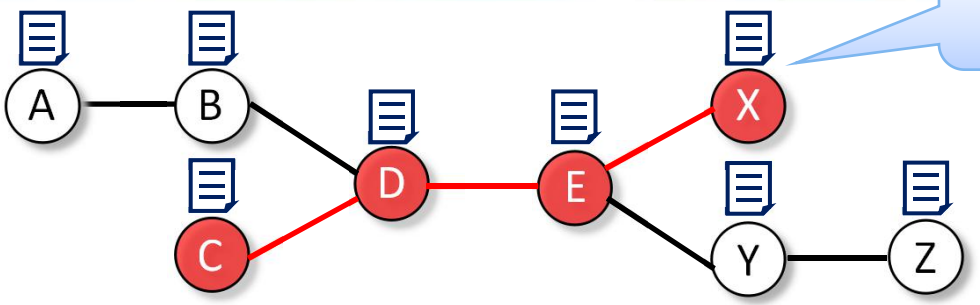


FD-PaS Framework

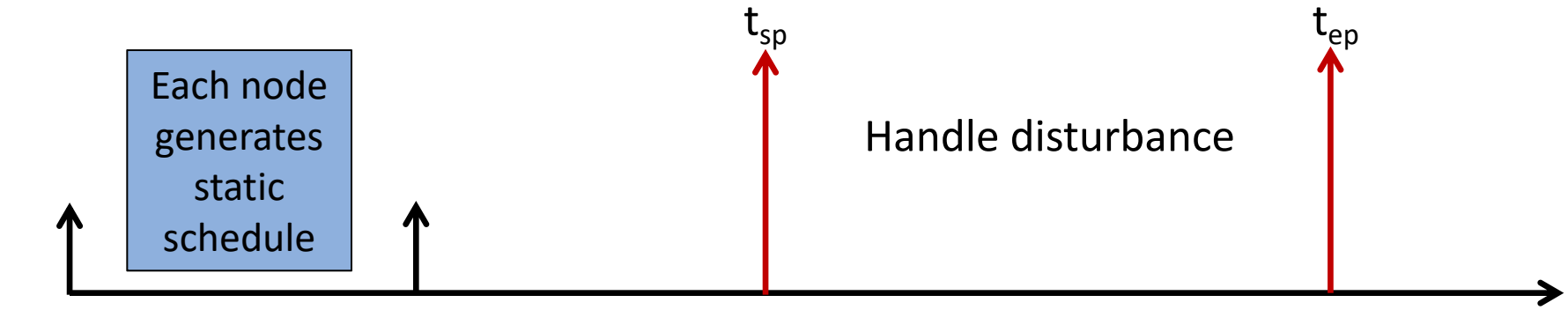


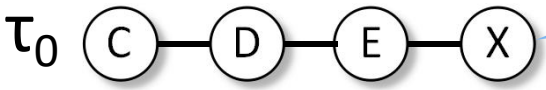


FD-PaS Framework



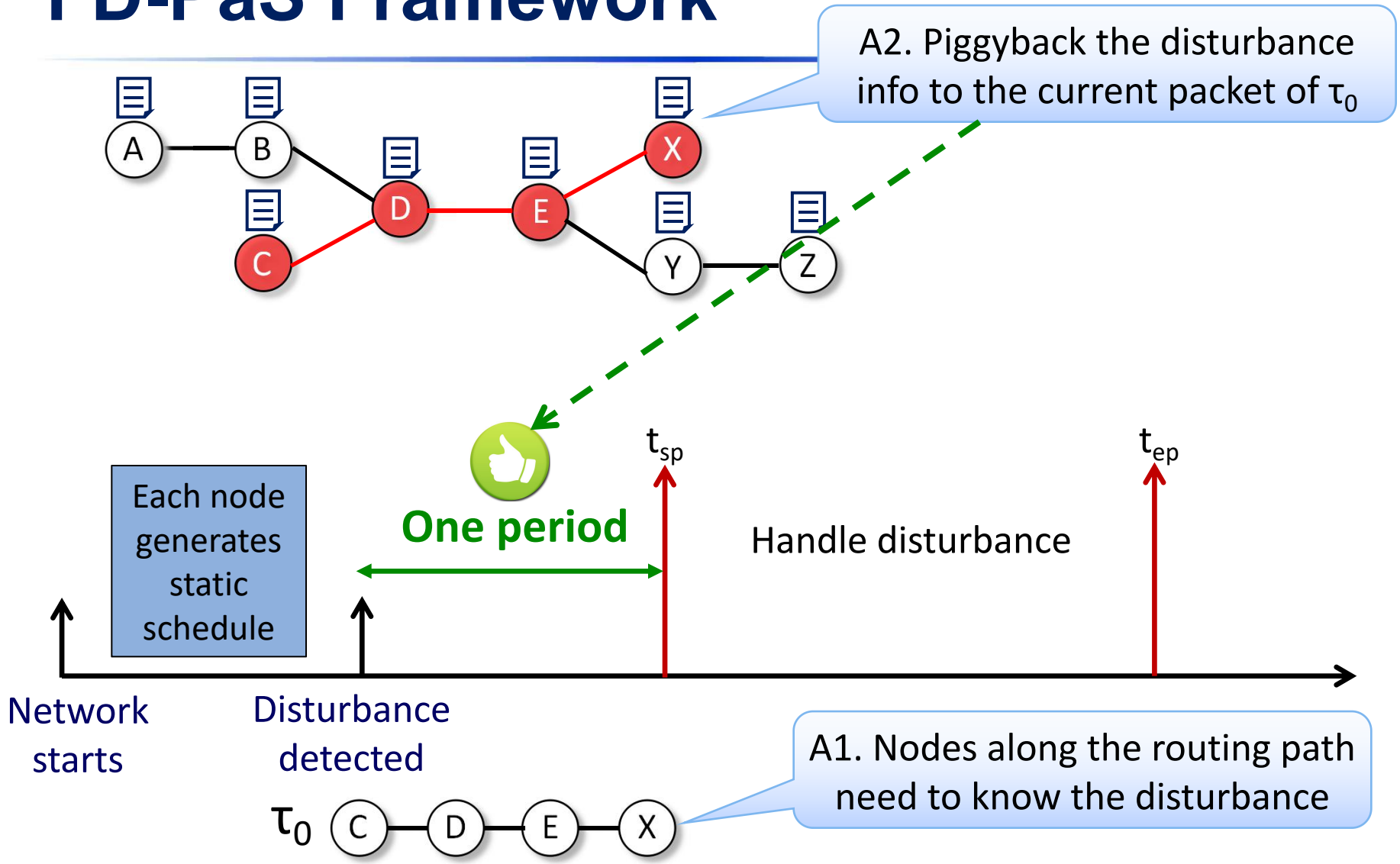
A2. Piggyback the disturbance info to the current packet of τ_0



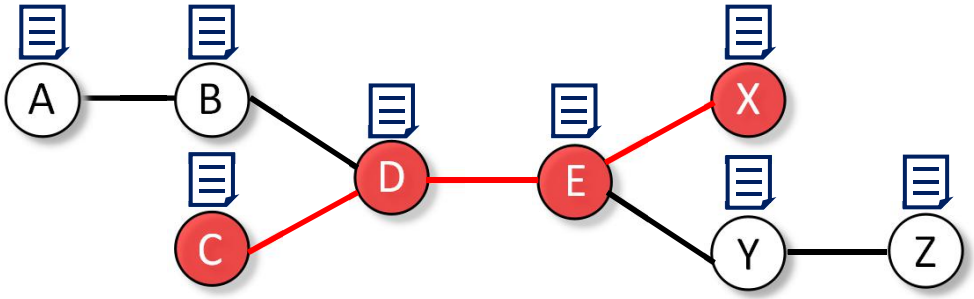


A1. Nodes along the routing path need to know the disturbance

FD-PaS Framework



FD-PaS Framework



Dynamic $\overline{S}$

C D E X

Static S

A B Y Z

t_{sp}

t_{ep}

Each node generates static schedule

Generate the dynamic schedule

Each node generates static schedule

Network starts

Disturbance detected

τ_0 C D E X

Challenges

- Transmission collisions among different nodes with inconsistent schedule would occur

- An efficient method is needed at each node to determine a dynamic schedule

Challenges

- Transmission collisions among different nodes with inconsistent schedule would occur

MP-MAC (Multi-priority wireless packet preemption)

- An efficient method is needed at each node to determine a dynamic schedule

Challenges

- Transmission collisions among different nodes with inconsistent schedule would occur

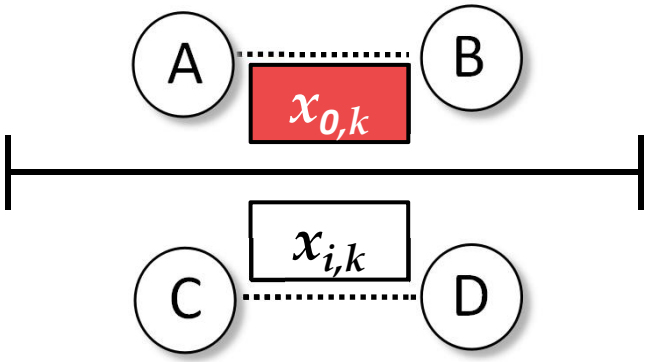
MP-MAC (Multi-priority wireless packet preemption)

- An efficient method is needed at each node to determine a dynamic schedule

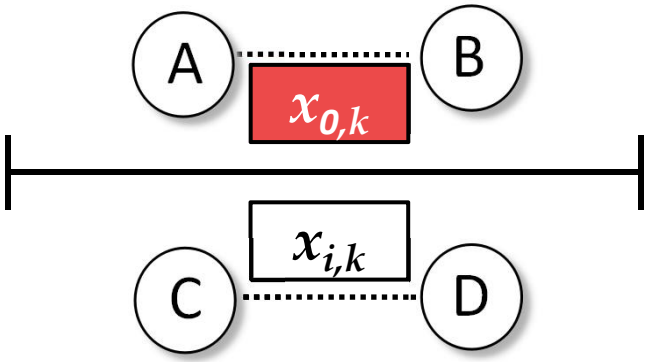
Formulate the packet dropping problem

Introduce an efficient heuristic

Avoid Transmission Collisions

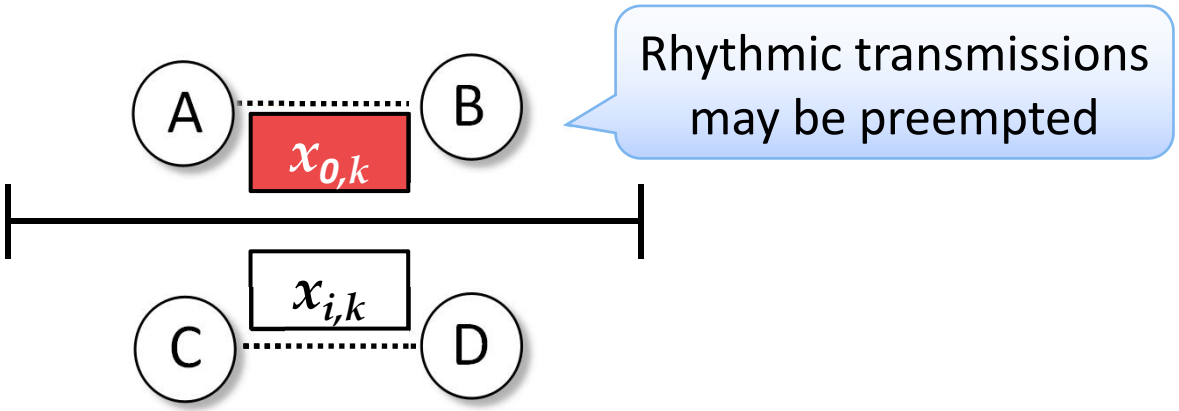


Avoid Transmission Collisions



- Currently
  - Most TDMA-based RTWN protocols employ the Clear Channel Assessment (CCA)
  - CCA cannot prioritize packet transmission

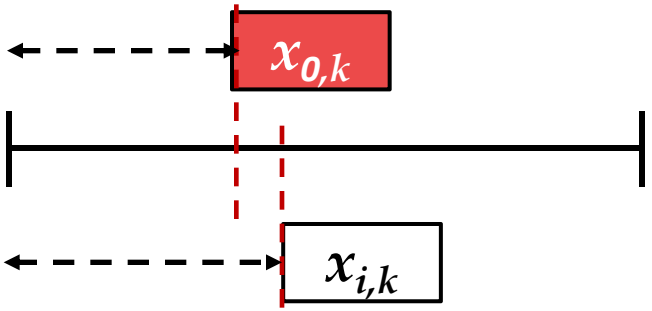
Avoid Transmission Collisions



- Currently
  - Most TDMA-based RTWN protocols employ the Clear Channel Assessment (CCA)
  - CCA cannot prioritize packet transmission
  - No guarantee on which packet is granted the channel access

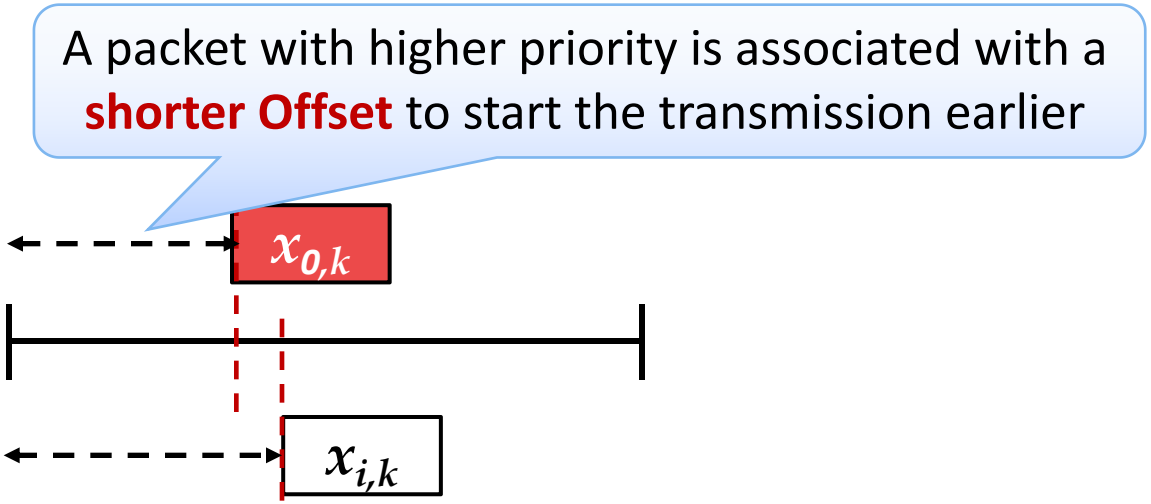
Multi-Priority MAC (MP-MAC)

- Give higher priority to rhythmic packets
  - Adjusting the Start-Of-Frame (SOF) time offset to indicate transmission priority



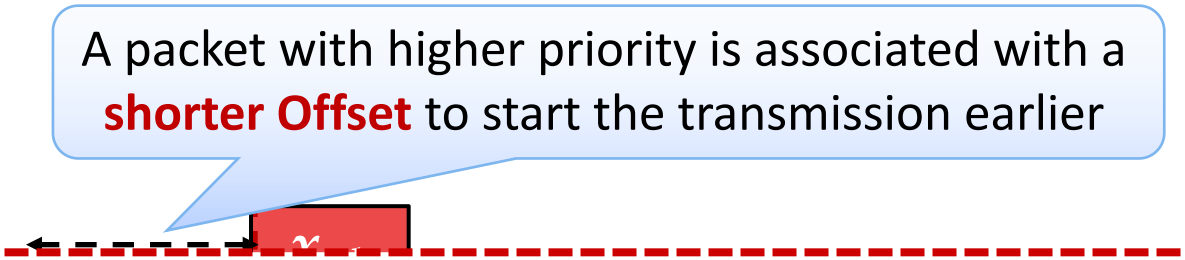
Multi-Priority MAC (MP-MAC)

- Give higher priority to rhythmic packets
  - Adjusting the Start-Of-Frame (SOF) time offset to indicate transmission priority



Multi-Priority MAC (MP-MAC)

- Give higher priority to rhythmic packets
  - Adjusting the Start-Of-Frame (SOF) time offset to indicate transmission priority



MP-MAC guarantees the rhythmic transmissions in the dynamic schedule are always successful

Challenges

- Transmission collisions among different nodes with inconsistent schedule would occur

Multi-priority wireless packet preemption mechanism

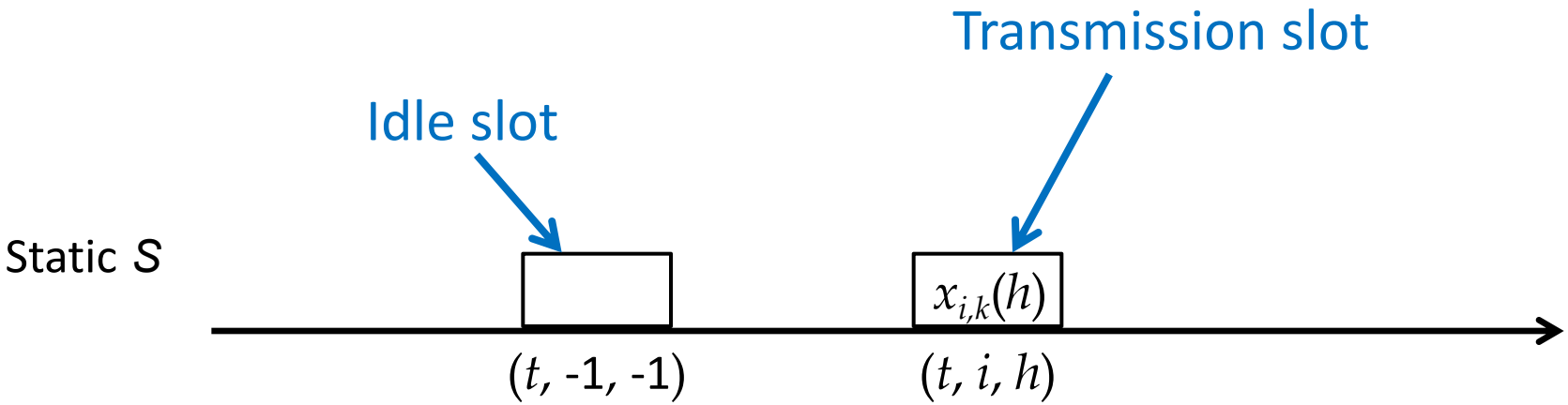
- An efficient method is needed at each node to determine a dynamic schedule

Formulate the packet dropping problem

Introduce an efficient heuristic

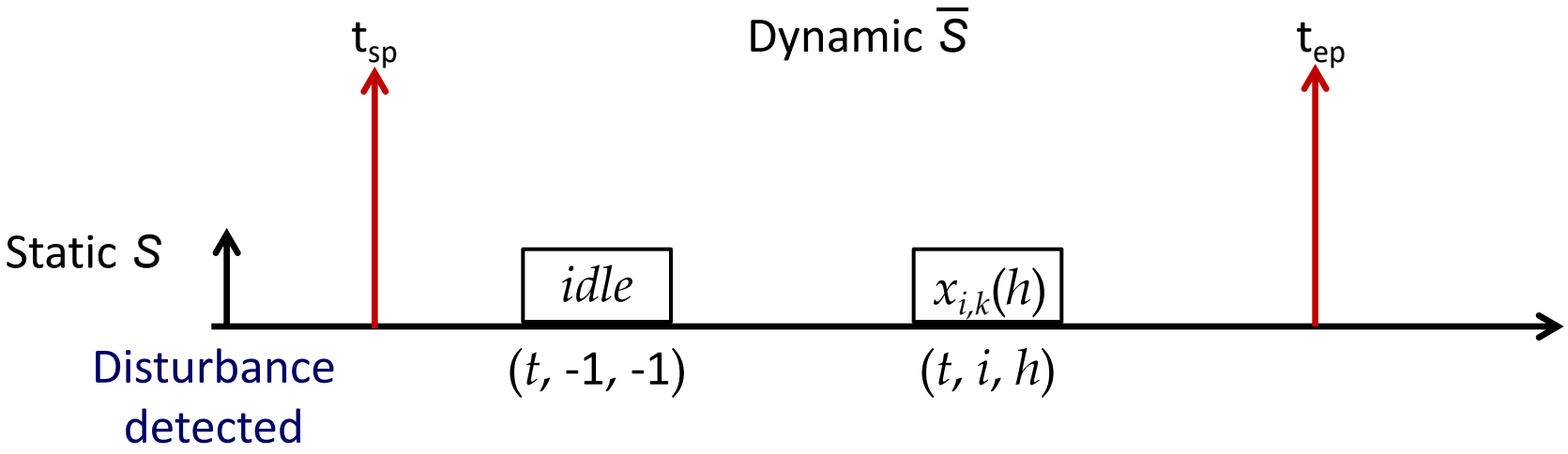
Packet Dropping Problem

- No disturbance: all nodes follow the static schedule



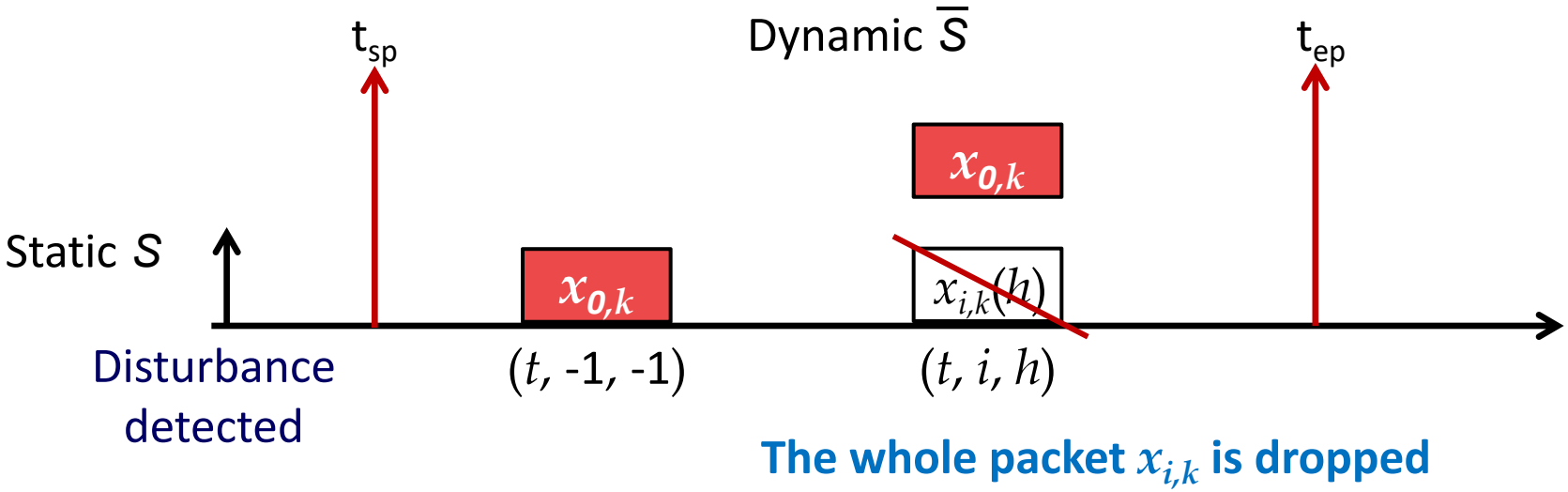
Packet Dropping Problem

- No disturbance: all nodes follow the static schedule
- Disturbance detected: a dynamic schedule is needed to accommodate the increased rhythmic workload $x_{0,k}$



Packet Dropping Problem

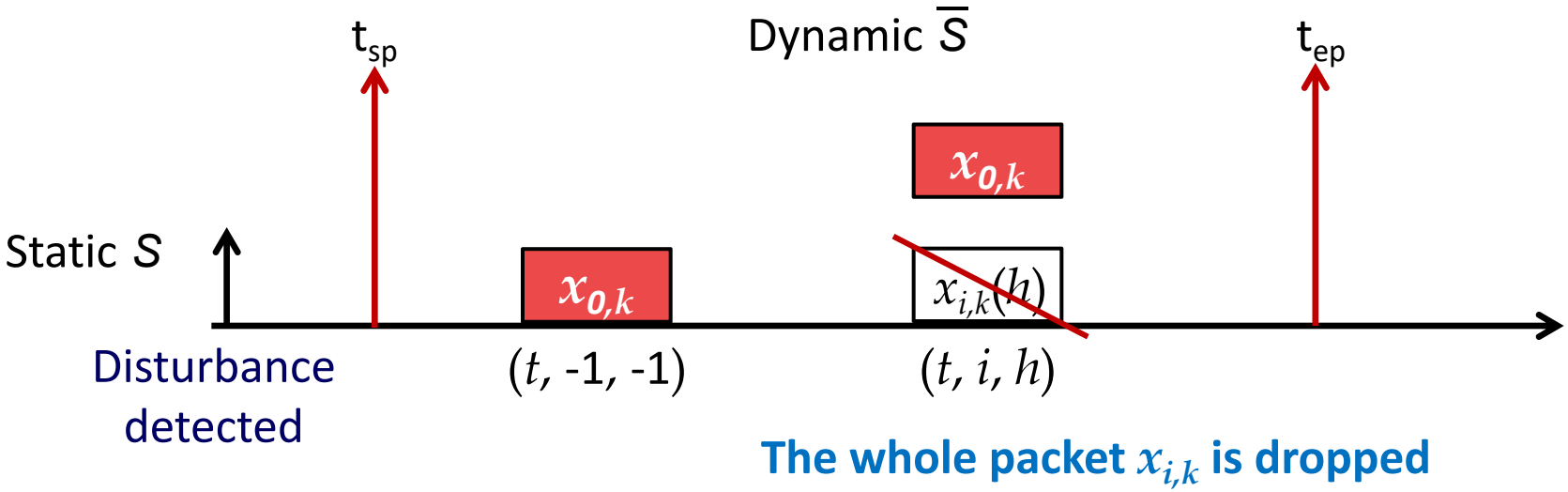
- No disturbance: all nodes follow the static schedule
- Disturbance detected: a dynamic schedule is needed to accommodate the increased rhythmic workload
  - Use idle slots
  - Drop some periodic transmissions



Packet Dropping Problem

- No disturbance: all nodes follow the static schedule
- Disturbance detected: a dynamic schedule is needed to accommodate the increased rhythmic workload
  - Use idle slots
  - Drop some periodic transmissions

How to choose periodic transmissions to be replaced?



The whole packet $x_{i,k}$ is dropped

Packet Dropping Problem Formulation

- Given $[t_{sp}, t_{ep})$, rhythmic packet set and static schedule *S*, determine the **dynamic schedule $\overline{S}$** in which the fewest periodic packets are dropped and
  - All rhythmic packets meet their deadlines
  - Any periodic transmission can only either be replaced or kept unchanged

Strongly NP-Hard!

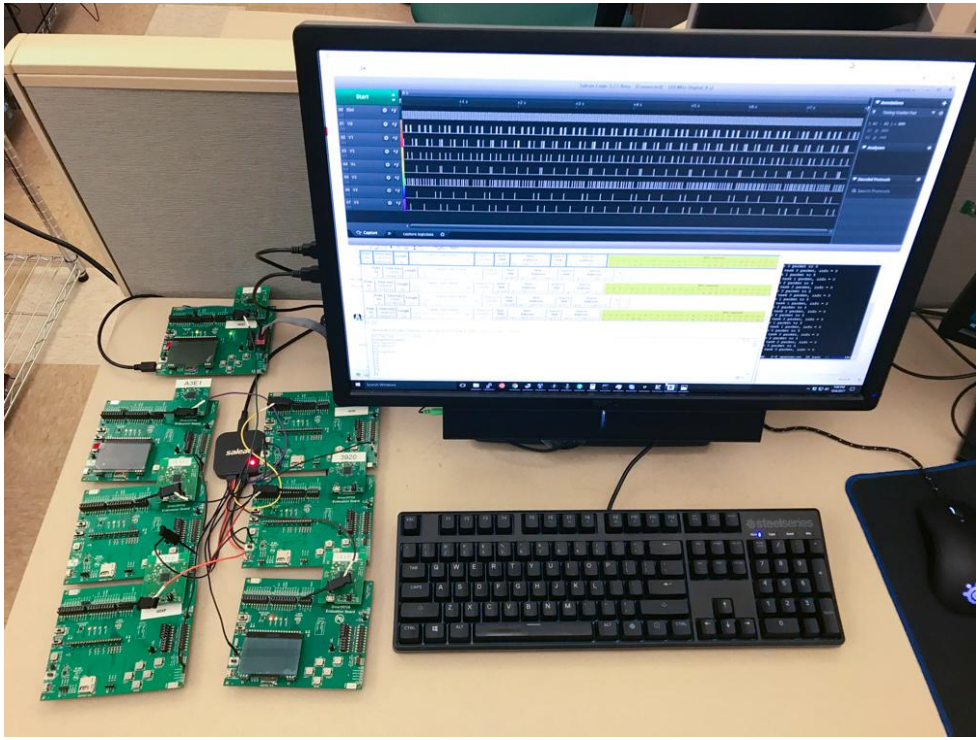
- **Heuristic**: drop the periodic packet that can give up the most slots to all rhythmic packets

Outline

- System model & related work
- Fully distrubuted packet scheduling framework (FD-Pas)
- **Experimental evaluation**
  - **Testbed**
  - **Simulation**

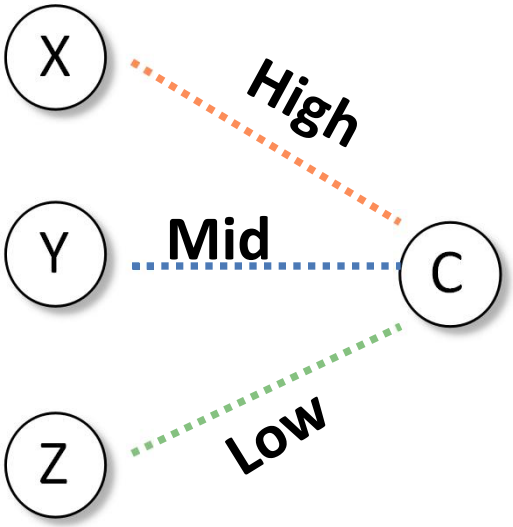
Testbed

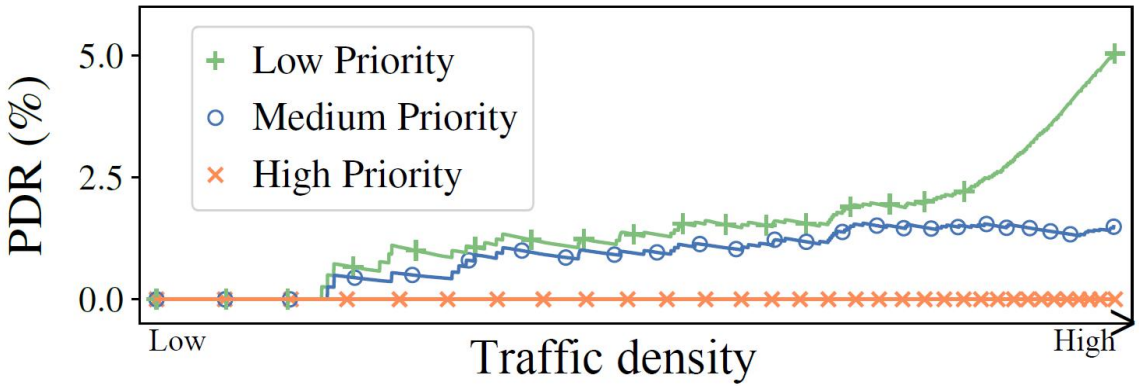
- FD-PaS on a 6TiSCH testbed (a real-time IoT protocol)
- MP-MAC through enhancing the slot timing in the data link layer
- Dynamic schedule generation in the application layer



MP-MAC Validation

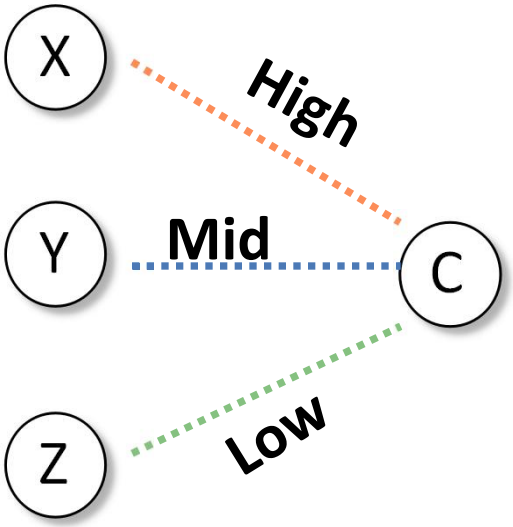
- Functional correctness
  - Higher priority packets can preempt lower ones

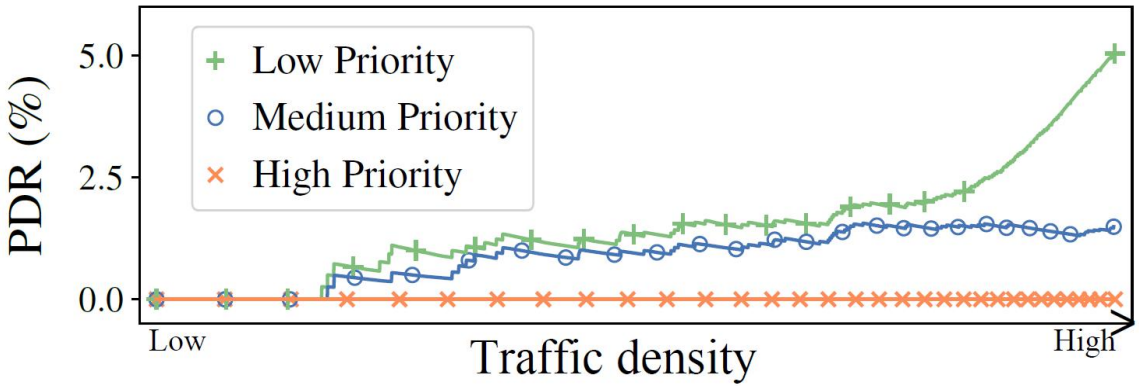




MP-MAC Validation

- Functional correctness
  - Higher priority packets can preempt lower ones

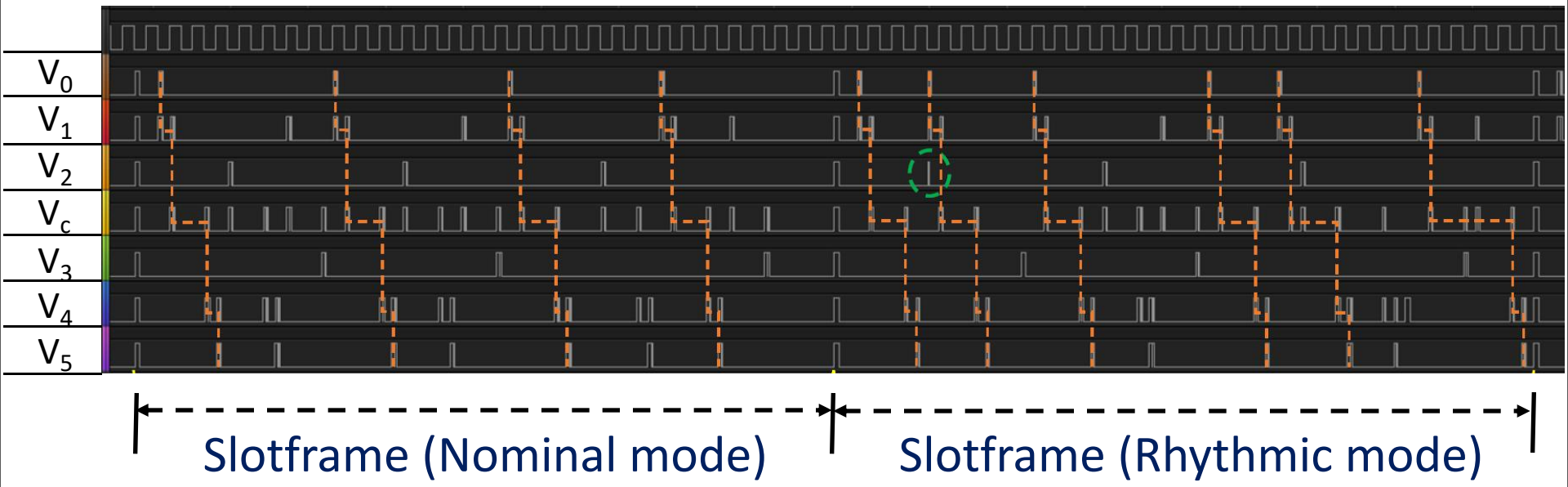




More experimental results in the paper and join us at our demo

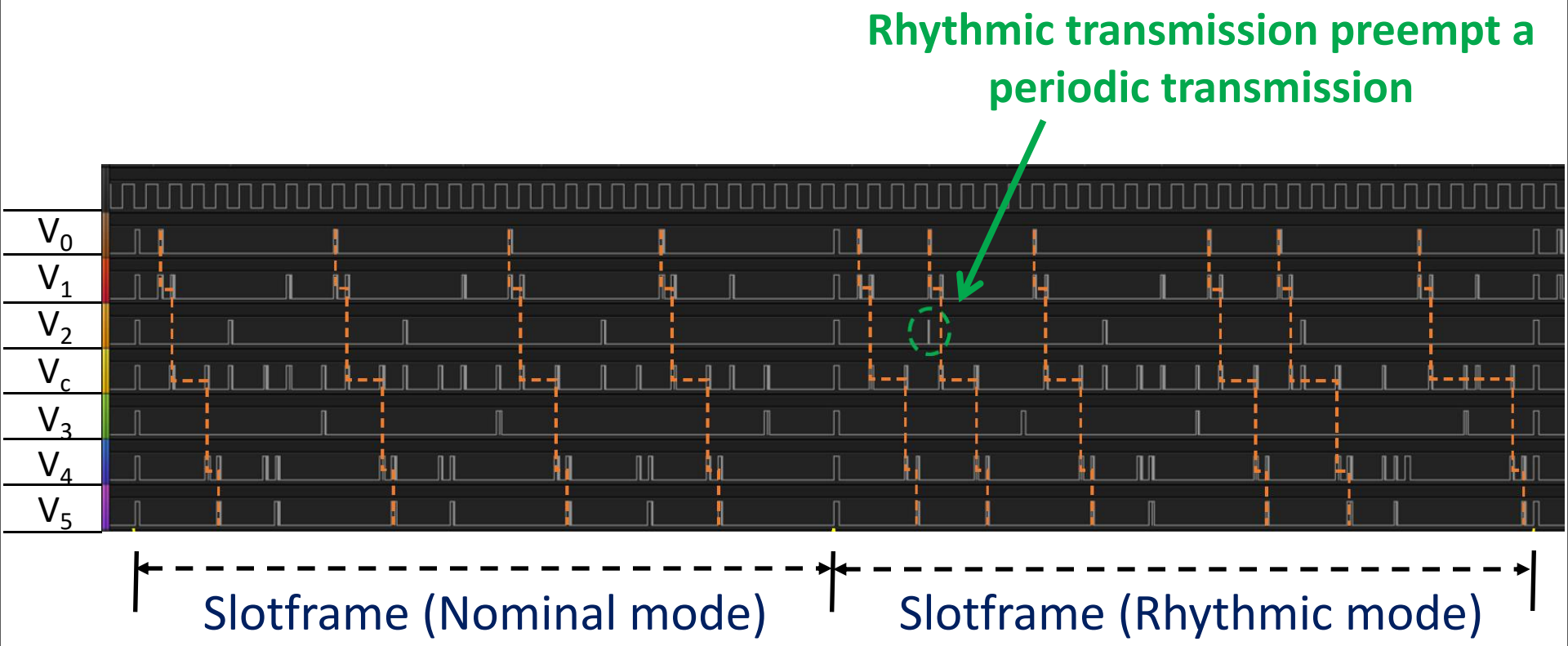
FD-PaS Validation

- Functional validation in a multi-task multi-hop RTWN
  - Use a logic analyzer to capture the radio activities from a pin of each device



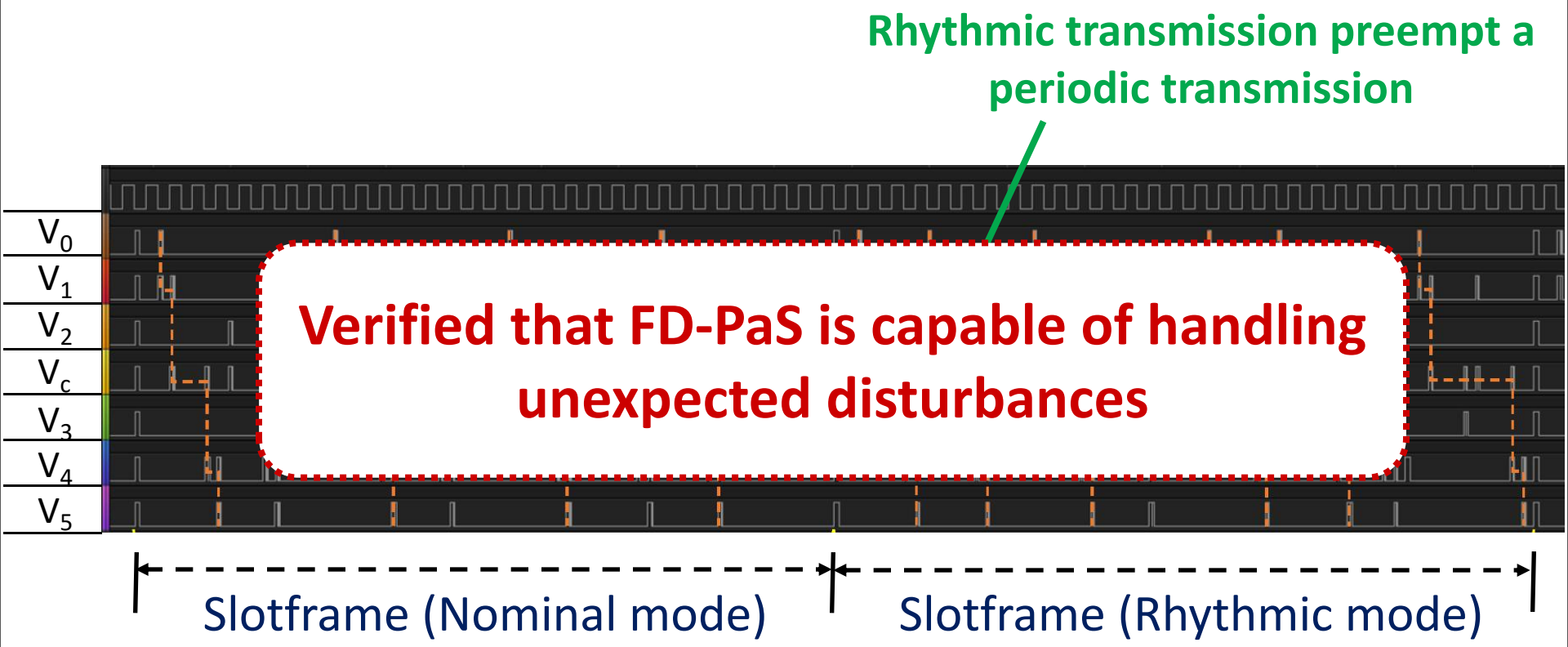
FD-PaS Validation

- Functional validation in a multi-task multi-hop RTWN
  - Use a logic analyzer to capture the radio activities from a pin of each device



FD-PaS Validation

- Functional validation in a multi-task multi-hop RTWN
  - Use a logic analyzer to capture the radio activities from a pin of each device



Simulation

Setup

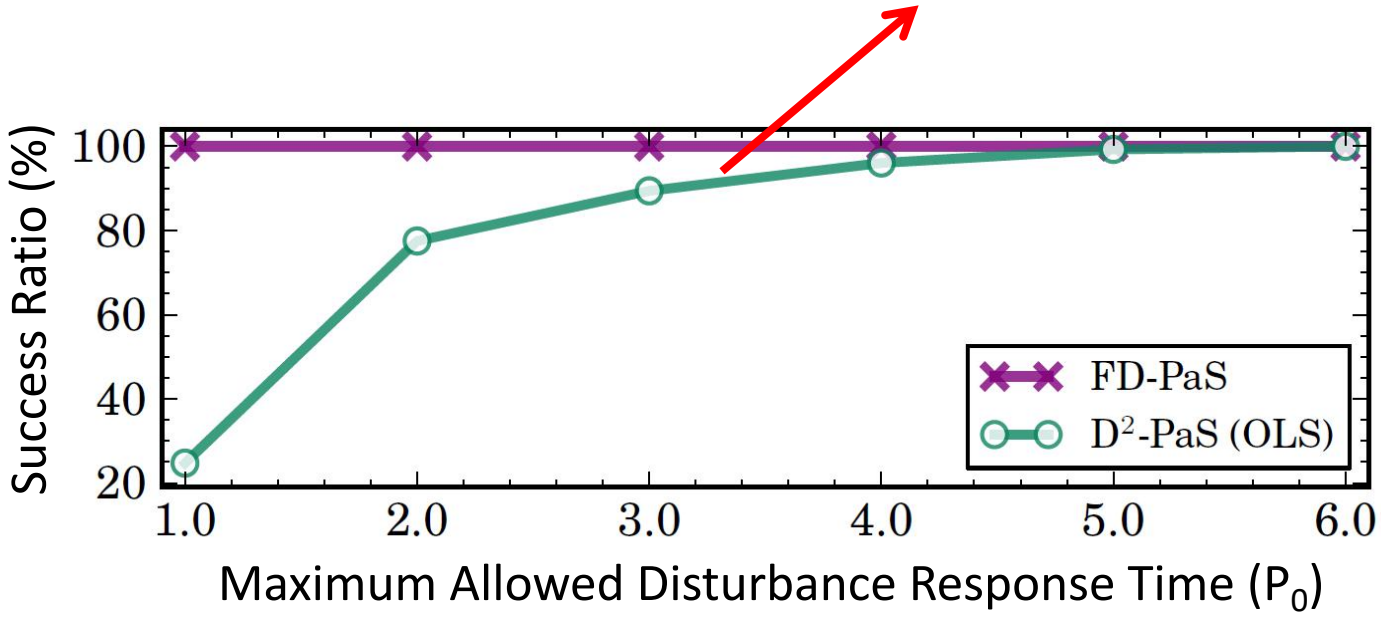
- Randomly generated task sets (based on realistic RTWN applications)
- Compare with OLS and D^2-PaS

Evaluation metrics

- **How fast is FD-PaS in responsing a disturbance?**
  - Success ratio (SR) = Feasible task sets / All the generated task sets.
- **How effective is FD-PaS in reducing dropped packets?**
  - Drop rate (DR) = Number of dropped packets / Total number of generated packets.

Simulation Results

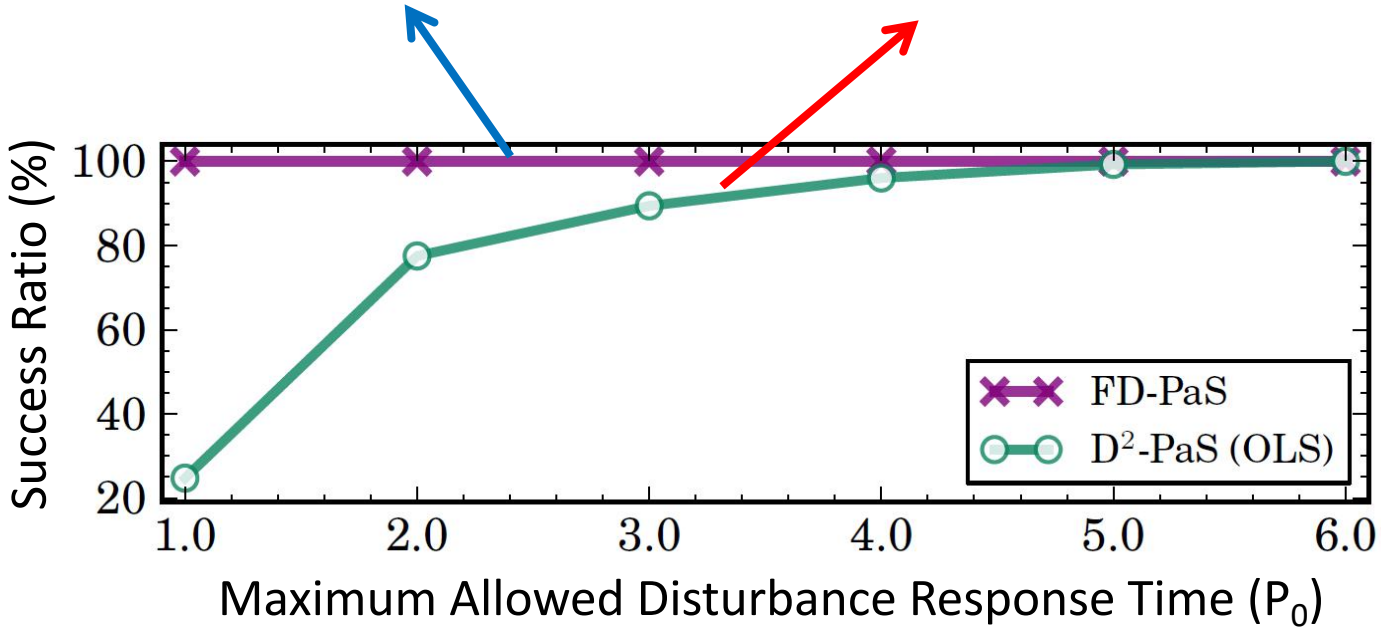
OLS and D²-PaS only feasible if DRT ≥ 6 periods



Simulation Results

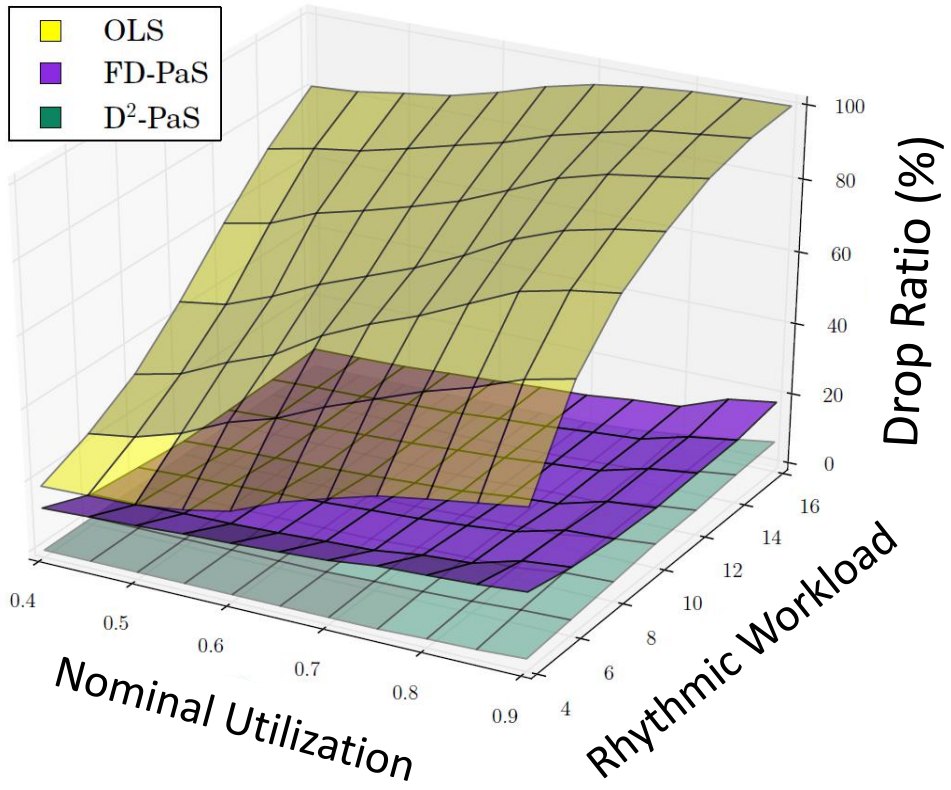
FD-PaS can always achieve 100% SR

OLS and D²-PaS only feasible if DRT ≥ 6 periods



Simulation Results

- FD-PaS has significantly lower DR over OLS (82% max and 53% on avg.)
- Compared to D²-PaS, FD-PaS drops around 12% more packets on average



Summary and Future Work

- Summary
  - Proposed the **first fully distributed** dynamic **fast response** framework for handling disturbances in RTWNs
    - Colission avoidance
    - Packet dropping

Summary and Future Work

- Summary
  - Proposed the **first fully distributed** dynamic **fast response** framework for handling disturbances in RTWNs
    - Colission avoidance
    - Packet dropping
  - Implemented the proposed framework on a testbed
  - Validated the correctness of the framework on the testbed

Summary and Future Work

- Summary
  - Proposed the **first fully distributed** dynamic **fast response** framework for handling disturbances in RTWNs
    - Colission avoidance
    - Packet dropping
  - Implemented the proposed framework on a testbed
  - Validated the correctness of the framework on the testbed
  - Evaluated the effectiveness of the framework

Summary and Future Work

- Summary
  - Proposed the **first fully distributed** dynamic **fast response** framework for handling disturbances in RTWNs
    - Colission avoidance
    - Packet dropping
  - Implemented the proposed framework on a testbed
  - Validated the correctness of the framework on the testbed
  - Evaluated the effectiveness of the framework
- Future work
  - Handle concurrent disturbances
  - Consider unreliable networks
  - Support multiple communication channels

Thank you!

Questions?

UCONN
UNIVERSITY OF CONNECTICUT

UNIVERSITY OF
NOTRE DAME